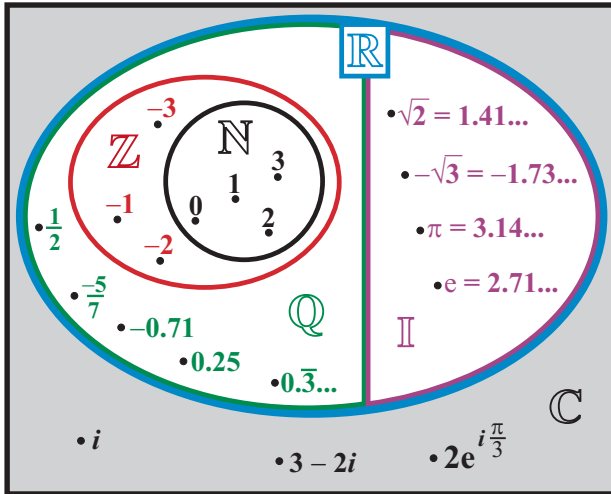


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1 Number Systems



- **Natural numbers:** $\mathbb{N} = \{0, 1, 2, 3, \dots\}$.
- **Integers:** $\mathbb{Z} = \{0, \pm 1, \pm 2, \dots\}$.
- **Rational numbers:** Set of all fractions: $\mathbb{Q} = \{\frac{m}{n} \mid m, n \in \mathbb{Z}, n \neq 0\}$. Numbers with periodic or terminating decimal expansion.
- **Irrational numbers I:** Numbers with infinite nonperiodic decimal expansion.
- **Real numbers \mathbb{R} :** Union of rational and irrational numbers.
- **Complex numbers:** $\mathbb{C} = \{x + iy \mid x, y \in \mathbb{R}\}$ with $i^2 = -1$.

Complex Numbers

► **Imaginary unit:** $i^2 = -1$

► **Euler's formula:**

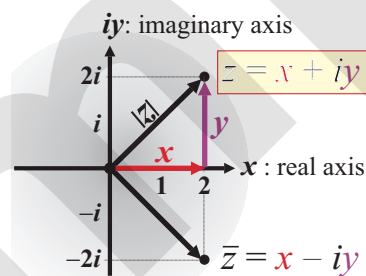
$$e^{i\varphi} = \cos(\varphi) + i \cdot \sin(\varphi)$$

$$e^{i\varphi} = \text{cis}(\varphi), \quad |e^{i\varphi}| = 1.$$

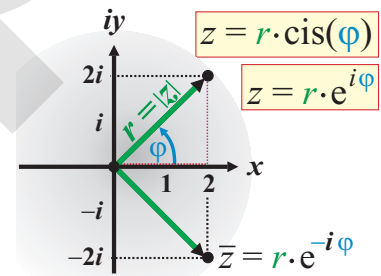
► **Argand diagram:**

xy -plane of the complex numbers.

Cartesian coordinates



Polar coordinates

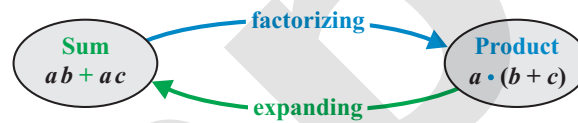


Complex number	z	$z = x + iy$ $\left\{ \begin{array}{l} x : \text{real part} \\ y : \text{imaginary part} \end{array} \right.$	$z = r \cdot e^{i\varphi} = r \cdot \text{cis}(\varphi)$
Complex conjugate	\bar{z}	$\bar{z} = x - iy$	$\bar{z} = r \cdot e^{-i\varphi}$
Modulus	$ z $	$ z = \sqrt{z \cdot \bar{z}} = \sqrt{x^2 + y^2}$	$ z = r = \sqrt{x^2 + y^2}$
Angle	φ	$x = r \cdot \cos(\varphi)$ $y = r \cdot \sin(\varphi)$	$\tan(\varphi) = \frac{y}{x}$ $\varphi = \arg(z)$
Addition Subtraction	$z_1 + z_2$ $z_1 - z_2$	$(x_1 \pm x_2) + i(y_1 \pm y_2)$	
Multiplication	$z_1 \cdot z_2$	$(x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)$	$r_1 \cdot r_2 \cdot e^{i(\varphi_1 + \varphi_2)}$
Division ($z_2 \neq 0$)	$\frac{z_1}{z_2}$	$\frac{z_1 \cdot \bar{z}_2}{ z_2 ^2} = \frac{(x_1 x_2 + y_1 y_2) + i(x_2 y_1 - x_1 y_2)}{x_2^2 + y_2^2}$	$\frac{r_1}{r_2} \cdot e^{i(\varphi_1 - \varphi_2)}$
Inverse ($z \neq 0$)	$\frac{1}{z}$	$\frac{\bar{z}}{ z ^2} = \frac{x - iy}{x^2 + y^2}$	$\frac{1}{r} \cdot e^{-i\varphi}$
Powers	z^n	$r^n \cdot (\cos(n \cdot \varphi) + i \sin(n \cdot \varphi)) = r^n \cdot e^{in\varphi}$	
Roots	$\sqrt[n]{z}$	$\sqrt[n]{r} \cdot (\cos(\frac{\varphi + 2\pi k}{n}) + i \sin(\frac{\varphi + 2\pi k}{n})), \quad k = 0, 1, \dots, (n-1)$	

2 Algebra

2.1 Addition and Multiplication, Basic Laws

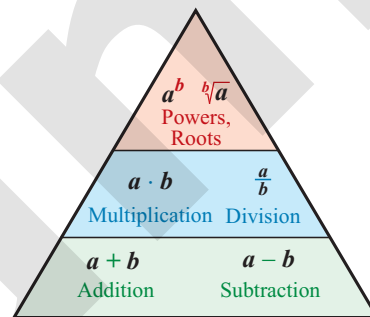
	Addition	Multiplication
Commutative law	$a + b = b + a$	$a \cdot b = b \cdot a$
Associative law	$(a + b) + c = a + (b + c) = a + b + c$	$(a \cdot b) \cdot c = a \cdot (b \cdot c) = a \cdot b \cdot c$
Distributive law	$a \cdot (b \pm c) = a \cdot b \pm a \cdot c$	
Neutral element	$a + 0 = 0 + a = a$	$a \cdot 1 = 1 \cdot a = a$
Inverse element	$a + (-a) = (-a) + a = 0$	$a \cdot (a^{-1}) = (a^{-1}) \cdot a = 1$



2.2 Order of Operators

Optional brackets:

- $-1^2 = -(1)^2 = -1$
- $2 \cdot 3^4 = 2 \cdot (3^4) = 162$
- $4 / 2 + 3 = (4 / 2) + 3 = 5$
- $2 + 3 \cdot 4 = 2 + (3 \cdot 4) = 14$



Mandatory brackets:

- $(-1)^2 = (-1) \cdot (-1) = +1$
- $(2 \cdot 3)^4 = 6^4 = 1296$
- $4 / (2 + 3) = 4 / 5 = 0.8$
- $(2 + 3) \cdot 4 = 5 \cdot 4 = 20$

Mnemonic: The precedence rules can be memorized by the acronym **BEDMAS**:

Brackets → Exponents, roots → Division, Multiplication → Addition, Subtraction.

2.3 Equivalence Transformations

Equation $a = b$		Inequality $a < b$
$a \pm c = b \pm c$	Addition, Subtraction	$a \pm c < b \pm c$
$a \cdot c = b \cdot c$	Multiplication by $c \neq 0$	$a \cdot c < b \cdot c$ if $c > 0$ $a \cdot c > b \cdot c$ if $c < 0$ [*]
$\frac{a}{c} = \frac{b}{c}$	Division by $c \neq 0$	$\frac{a}{c} < \frac{b}{c}$ if $c > 0$ $\frac{a}{c} > \frac{b}{c}$ if $c < 0$ [*]
$\frac{1}{a} = \frac{1}{b}$	Reciprocal ($a, b \neq 0$)	$\frac{1}{a} < \frac{1}{b}$ if $a \cdot b < 0$ $\frac{1}{a} > \frac{1}{b}$ if $a \cdot b > 0$ [*]

[*]: Inequality changes direction.

2.4 Binomial Formulae, Binomial Theorem

Binomial formulae:

1st formula: $(a + b)^2 = a^2 + 2 \cdot a \cdot b + b^2$

2nd formula: $(a - b)^2 = a^2 - 2 \cdot a \cdot b + b^2$

3rd formula: $(a + b) \cdot (a - b) = a^2 - b^2$

• $a^2 + b^2$ irreducible in \mathbb{R} .

• $a^3 + b^3 = (a + b) \cdot (a^2 - a \cdot b + b^2)$

• $a^3 - b^3 = (a - b) \cdot (a^2 + a \cdot b + b^2)$

• $a^n - b^n = (a - b) \cdot \sum_{k=0}^{n-1} a^{n-1-k} \cdot b^k$

Binomial theorem:

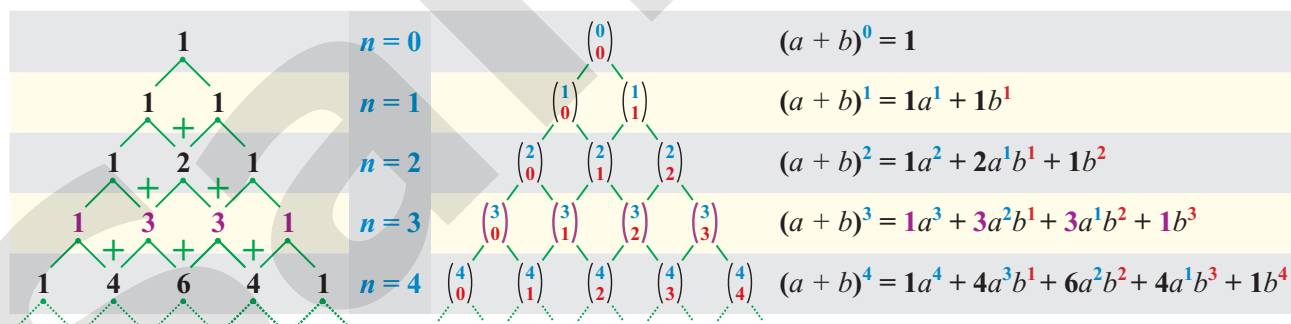
$$(a + b)^n = \underbrace{\binom{n}{0}}_{=1} a^n b^0 + \binom{n}{1} a^{n-1} b^1 + \binom{n}{2} a^{n-2} b^2 + \dots + \underbrace{\binom{n}{n}}_{=1} a^0 b^n = \sum_{k=0}^n \binom{n}{k} a^{n-k} \cdot b^k$$

• Binomial coefficients: $\binom{n}{k} = \frac{n!}{k! \cdot (n-k)!}$.

• Factorial: $n! = 1 \cdot 2 \cdot \dots \cdot n$, $0! = 1! = 1$. (\Rightarrow See combinatorics on p. 36)

• For $(a - b)^n$ the sign is *alternating*: $(a - b)^3 = +a^3 - 3a^2b + 3ab^2 - b^3$.

Pascal's triangle and binomial theorem:



Absolute value: $|x| = \sqrt{x^2} = \begin{cases} x & \text{if } x \geq 0 \\ -x & \text{if } x < 0 \end{cases}$

„makes x positive”. See p. 15.

2.5 Fractions

Addition, Subtraction	$\frac{a}{b} \pm \frac{x}{y} = \frac{a \cdot y}{b \cdot y} \pm \frac{x \cdot b}{y \cdot b} = \frac{a \cdot y \pm x \cdot b}{b \cdot y}$ $b, y \neq 0$	► Put onto the common denominator, then add the numerators.
Multiplication	$\frac{a}{b} \cdot \frac{x}{y} = \frac{a \cdot x}{b \cdot y}$ $b, y \neq 0$	► Multiply numerators and denominators separately.
Division, compound fractions	$\frac{a}{b} : \frac{x}{y} = \frac{\frac{a}{b}}{\frac{x}{y}} = \frac{a}{b} \cdot \frac{y}{x}$ $b, x, y \neq 0$	► Dividing by a fraction = multiplying by its reciprocal.

2.6 Powers

Definition: $a^n = \underbrace{a \cdot a \cdot \dots \cdot a}_{n \text{ factors}}$ is called the n^{th} power of a , where $\begin{cases} a \in \mathbb{R} & : \text{Base} \\ n \in \mathbb{N} & : \text{Exponent.} \end{cases}$

Particularly: $a^1 = a$ and $\begin{cases} a^0 = 1, & \text{if } a \neq 0 \\ 0^n = 0, & \text{if } n > 0. \end{cases}$

• **Negative exponents:** $k \cdot a^{-n} = \frac{k}{a^n}$ $a \neq 0$.

• **Rational exponents:** $a^{\frac{m}{n}} = \sqrt[n]{a^m}$ $a \geq 0, n > 0$.

Particularly: $a^{\frac{1}{n}} = \sqrt[n]{a}$ Square root ($n = 2$): $\sqrt{a} = a^{\frac{1}{2}}$

Power laws

Same base	$a^n \cdot a^m = a^{n+m}$	$\frac{a^n}{a^m} = a^{n-m}$	$a \neq 0$
Same exponent	$a^n \cdot b^n = (a \cdot b)^n$	$\frac{a^n}{b^n} = \left(\frac{a}{b}\right)^n$	$b \neq 0$
	$\sqrt[n]{a} \cdot \sqrt[n]{b} = \sqrt[n]{a \cdot b}$	$\frac{\sqrt[n]{a}}{\sqrt[n]{b}} = \sqrt[n]{\frac{a}{b}}$	$b \neq 0$
Powers of powers	$(a^n)^m = a^{n \cdot m} = (a^m)^n$	$\sqrt[m]{\sqrt[n]{a}} = \sqrt[nm]{a} = \sqrt[n]{\sqrt[m]{a}}$	$a \geq 0$

2.7 Logarithms (see p. 18)

Definition	$\log_a(x) = y \Leftrightarrow a^y = x$	$a, x > 0, a \neq 1$
Multiplication, Division	$\log_a(x \cdot y) = \log_a(x) + \log_a(y)$	$\log_a\left(\frac{x}{y}\right) = \log_a(x) - \log_a(y)$
Powers	$\log_a(x^y) = y \cdot \log_a(x)$ $x > 0$	$a^x = b \Rightarrow x = \frac{\ln(b)}{\ln(a)}$
Change of base	$\log_a(x) = \frac{\log_b(x)}{\log_b(a)}$ $a > 0; a \neq 1$ $b > 0; b \neq 1$	especially: $\log_a(x) = \frac{\ln(x)}{\ln(a)}$

\Rightarrow See Logarithmic functions on p. 18.

3 Plane Geometry

3.1 Triangles

- Sum of angles: $\alpha + \beta + \gamma = 180^\circ$

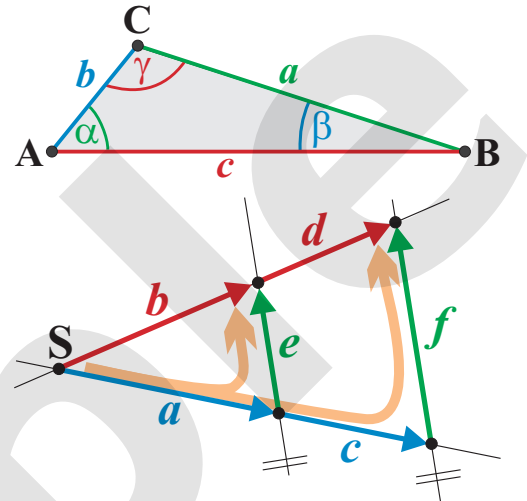
- Triangle inequality: $c < a + b$

- Intercept theorems (proportionality):

Two triangles are called similar if they have the same angles. Equivalently, the ratios of their sides are equal.

1st Intercept theorem: $\frac{a}{b} = \frac{c}{d} = \frac{a+c}{b+d}$

2nd Intercept theorem: $\frac{a}{e} = \frac{a+c}{f}$



- Sine rule: $\frac{a}{\sin(\alpha)} = \frac{b}{\sin(\beta)} = \frac{c}{\sin(\gamma)} = 2 \cdot R$

R : Radius of the circumcircle.

- Cosine rule: $c^2 = a^2 + b^2 - 2 \cdot a \cdot b \cdot \cos(\gamma)$

cyclic permutations: $\begin{matrix} b & a \\ \curvearrowright & \\ c & b \end{matrix}$

- Area: $A_\Delta = \frac{1}{2} (\text{base} \cdot \text{height}) = \frac{c \cdot h_c}{2} = \frac{b \cdot h_b}{2} = \frac{a \cdot h_a}{2}$

- ▶ two sides and their enclosed angle: $A_\Delta = \frac{b \cdot c}{2} \cdot \sin(\alpha)$ cyclic perm.: $\begin{matrix} b & a \\ \curvearrowright & \\ c & b \end{matrix}$

- ▶ three sides (Heron): $A_\Delta = \sqrt{s(s-a)(s-b)(s-c)}$ with the semi-perimeter $s = \frac{1}{2}(a+b+c)$.

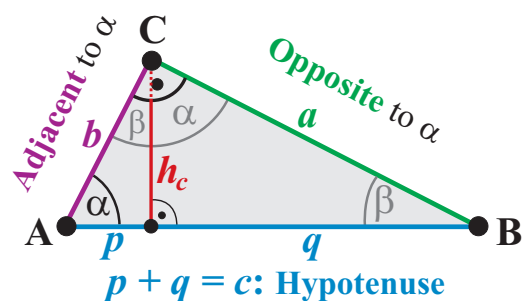
- ▶ three angles and R : $A_\Delta = 2 R^2 \cdot \sin(\alpha) \cdot \sin(\beta) \cdot \sin(\gamma)$ R : Radius of the circumcircle.

3.2 Right-angled Triangle

- Pythagoras' theorem: $c^2 = a^2 + b^2$

- Altitude theorem: $h_c^2 = p \cdot q$

- Euclid's theorem: $\begin{cases} a^2 = c \cdot q \\ b^2 = c \cdot p \end{cases}$



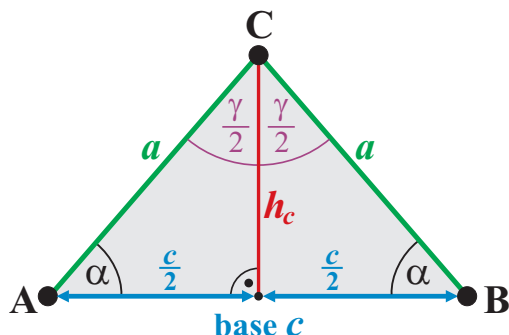
- Trigonometric functions: (see p. 19)

$$\sin(\alpha) = \frac{a}{c} \quad \cos(\alpha) = \frac{b}{c} \quad \tan(\alpha) = \frac{a}{b}$$

mnemonic:
SOH CAH TOA

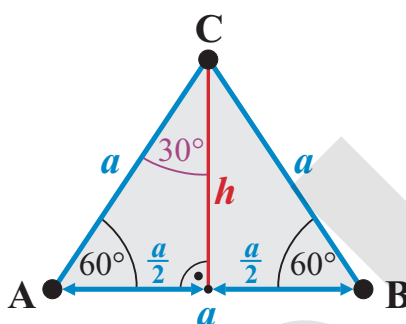
3.3 Isosceles and Equilateral Triangles

Isosceles triangle



- ▶ h_c bisects base c .
- ▶ h_c bisects angle γ .
- ▶ Equal base angles ($\alpha = \beta$).

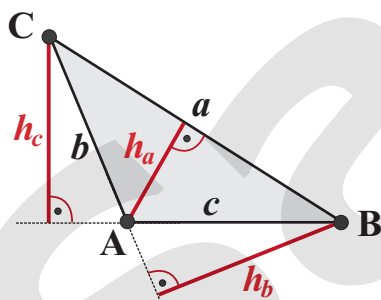
Equilateral triangle



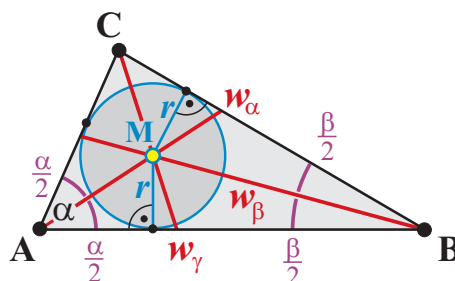
- ▶ Height: $h = \frac{\sqrt{3}}{2} a$.
- ▶ Area: $A = \frac{\sqrt{3}}{4} a^2$.
- ▶ Radius of the circumcircle: $R = \frac{\sqrt{3}}{3} a = \frac{2}{3} h$.
- ▶ Inradius: $r = \frac{\sqrt{3}}{6} a = \frac{1}{3} h$.

3.4 Lines in a Triangle

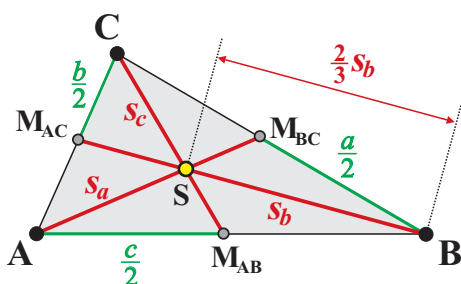
Heights are straight lines through a vertex **perpendicular** to the opposite side.



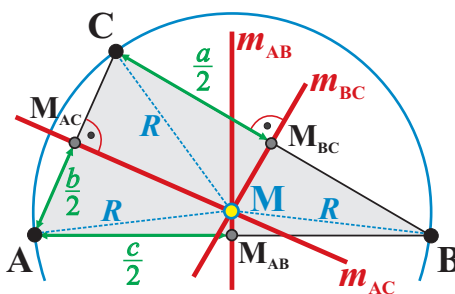
Angle bisectors bisect an angle of the triangle. Each point on an angle bisector has the **same distance** from the adjacent sides. Angle bisectors intersect at the **center M** of the **incircle**.



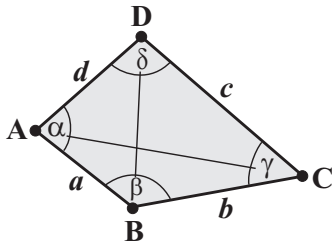
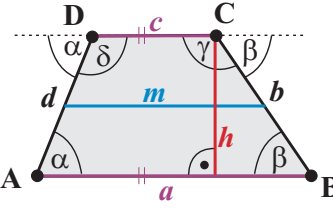
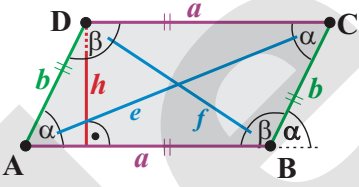
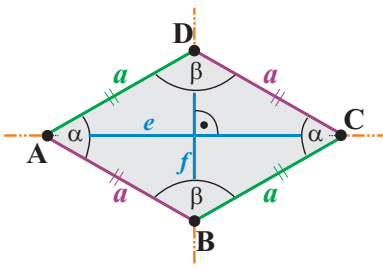
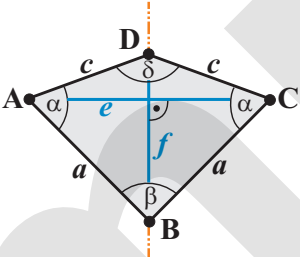
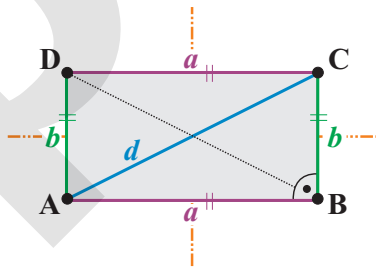
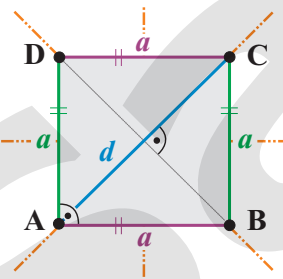
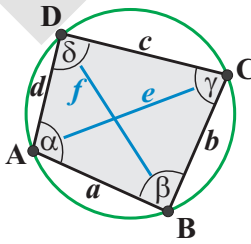
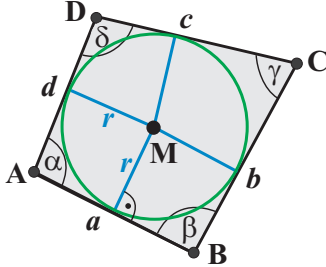
Medians are the lines from a vertex to the midpoint of the opposite side. They intersect in the **ratio 2:1**. The point of coincidence is the **centroid S** (center-of-mass) of the triangle. See p. 32.



Perpendicular bisectors are the set of points having the **same distance** from two vertices of the triangle. They intersect at the **center M** of the **circumcircle**.

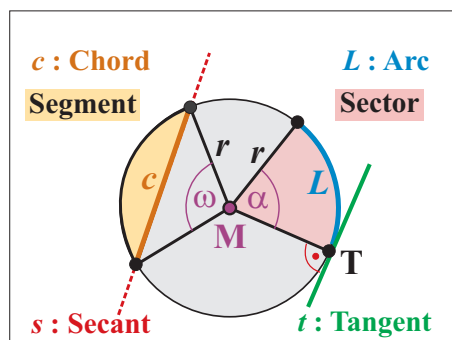


3.5 Quadrilaterals

<p>Quadrilateral</p>  <p>► $\alpha + \beta + \gamma + \delta = 360^\circ$</p>	<p>Trapezium, trapezoid</p>  <p>► $A = \frac{a+c}{2} \cdot h = m \cdot h$</p>	<p>Parallelogram, rhomboid</p>  <p>► $A = a \cdot h = a \cdot b \cdot \sin(\alpha)$</p>
<p>Rhombus</p>  <p>► $A = \frac{e \cdot f}{2} = a^2 \cdot \sin(\alpha)$</p>	<p>Kite</p>  <p>► $A = \frac{e \cdot f}{2} = a \cdot c \cdot \sin(\alpha)$</p>	<p>Rectangle</p>  <p>► $A = a \cdot b$</p>
<p>Square</p>  <p>► $A = a^2$ ► $d = a \cdot \sqrt{2}$</p>	<p>Cyclic quadrilateral</p>  <p>► $\alpha + \gamma = \beta + \delta = 180^\circ$ ► $a \cdot c + b \cdot d = e \cdot f$</p>	<p>Tangent quadrilateral</p>  <p>► $a + c = b + d$ ► $A = r \cdot \frac{a+b+c+d}{2}$</p>

Symmetry axis are shown in orange color.

3.6 Circle

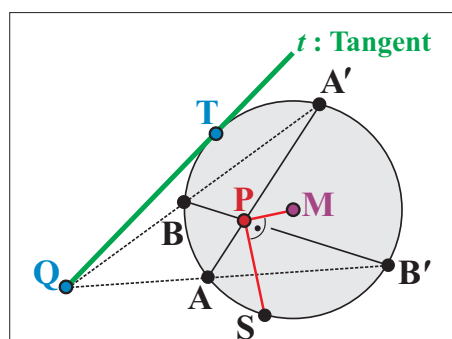


Circumference $C = 2\pi \cdot r$

Arc length $L = 2\pi r \cdot \frac{\alpha}{360^\circ}$

Area $A = \pi \cdot r^2$

Sector $A_{\text{sector}} = \pi r^2 \cdot \frac{\alpha}{360^\circ} = \frac{b \cdot r}{2}$

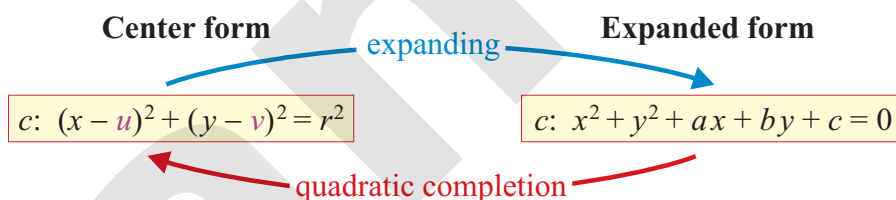


Segment $A_{\text{segment}} = r^2 \cdot \left(\pi \cdot \frac{\omega}{360^\circ} - \frac{1}{2} \cdot \sin(\omega) \right)$

Intersecting chord theorem $\overline{PA} \cdot \overline{PA'} = \overline{PB} \cdot \overline{PB'} = \overline{PS}^2$

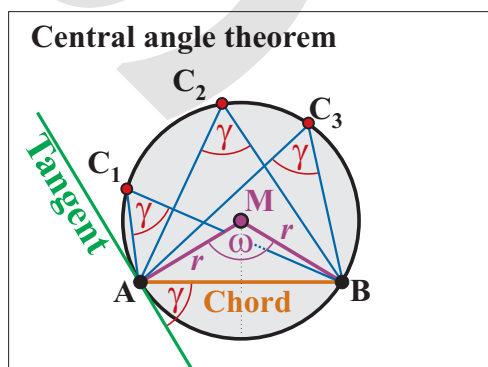
Intersecting secant theorem $\overline{QB} \cdot \overline{QA'} = \overline{QA} \cdot \overline{QB'} = \overline{QT}^2$

► Equation of circle c with center $M(u / v)$ and radius r :

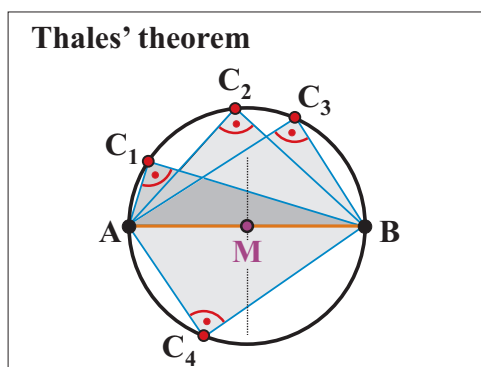


► Tangent t to c at point $T(x_0 / y_0)$: $t: (x - u) \cdot (x_0 - u) + (y - v) \cdot (y_0 - v) = r^2$

Circle Angle Theorems

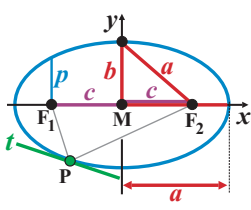
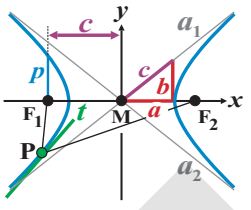
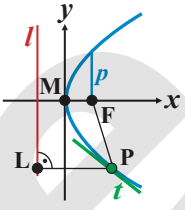


- Equal inscribed angle γ .
- Central angle $\omega = 2 \cdot \gamma$.



- Equal inscribed angle $\gamma = 90^\circ$.

3.7 Conic Sections

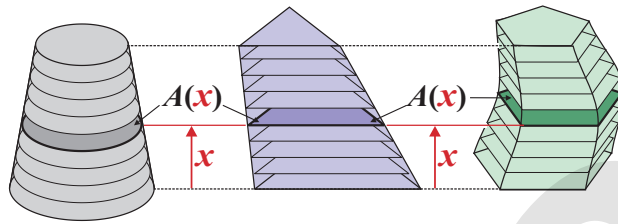
	Ellipse 	Hyperbola 	Parabola 
Distance property	$\overline{PF_1} + \overline{PF_2} = 2a$	$ \overline{PF_1} - \overline{PF_2} = 2a$	$\overline{PF} = \overline{PL}$
Equation for center $M(0 / 0)$	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$	$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$	$y^2 = 2 \cdot p \cdot x$
Parametric form for center $M(0 / 0)$	$x(\varphi) = a \cdot \cos(\varphi)$ $y(\varphi) = b \cdot \sin(\varphi)$	$x(\varphi) = \pm a \cdot \cosh(\varphi)$ $y(\varphi) = b \cdot \sinh(\varphi)$	
Tangent equation in $P(x_0 / y_0)$	$t: \frac{x x_0}{a^2} + \frac{y y_0}{b^2} = 1$	$t: \frac{x x_0}{a^2} - \frac{y y_0}{b^2} = 1$	$t: y y_0 = p(x + x_0)$
Tangent condition for $t: y = m_t x + q$	$q^2 = a^2 m_t^2 + b^2$	$q^2 = a^2 m_t^2 - b^2$	$q = \frac{p}{2m_t}$
Conjugated direction	$m_1 \cdot m_2 = -\frac{b^2}{a^2}$	$m_1 \cdot m_2 = +\frac{b^2}{a^2}$	
Linear eccentricity	$c^2 = a^2 - b^2$	$c^2 = a^2 + b^2$	
Numerical eccentricity	$\varepsilon = \frac{c}{a} < 1$	$\varepsilon = \frac{c}{a} > 1$	$\varepsilon = 1$
Focus	$F_{1,2}(\pm c / 0)$	$F_{1,2}(\pm c / 0)$	$F(\frac{p}{2} / 0)$
Radius of curvature	$r_a = \frac{b^2}{a}, r_b = \frac{a^2}{b}$	$r = \frac{b^2}{a}$	$r = p$
Parameter p	$p = \frac{b^2}{a}$	$p = \frac{b^2}{a}$	p
Area	$A = \pi \cdot a \cdot b$		
Asymptotes		$a_{1,2}: y = \pm \frac{b}{a} \cdot x$	

Translation from $M(0 / 0)$ to $M'(u / v)$: $\begin{cases} x \rightarrow (x - u) \\ y \rightarrow (y - v) \end{cases}$

4 Stereometry

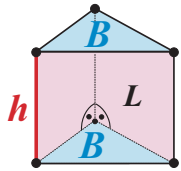
Cavalieri's Principle

Two solids have the same volume if their cross-sections $A(x)$ have the same area at all levels x .

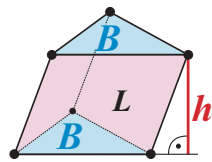


4.1 Prisms and Cylinders (Congruent, Parallel Base and Top Face B)

Right prism



Oblique prism



► B : Base area; L : Lateral area.

► h : Height.

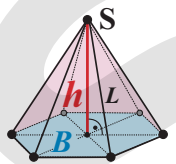
► Volume: $V = B \cdot h$

► Surface area: $A = 2 \cdot B + L$

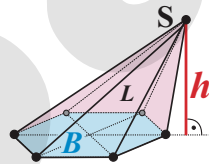
<p>Cuboid</p> <p>► $V = a \cdot b \cdot h$</p> <p>► $A = 2(a \cdot b + a \cdot h + b \cdot h)$</p> <p>► $D = \sqrt{a^2 + b^2 + h^2}$</p>	<p>Cube</p> <p>► $V = a^3$</p> <p>► $A = 6 \cdot a^2$</p> <p>► $D = a \cdot \sqrt{3}, \quad d = a \cdot \sqrt{2}$</p>	<p>Cylinder</p> <p>► $V = \pi r^2 \cdot h$</p> <p>► $A = 2 \cdot \pi r^2 + 2\pi r \cdot h$</p> <p>► $L = 2\pi r \cdot h$</p>
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4.2 Pyramids and Cones

Right pyramid



Oblique pyramid



► B : Base area; L : Lateral area.

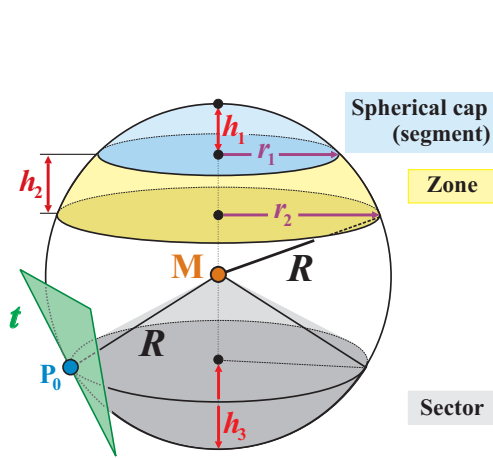
► h : Height.

► Volume: $V = \frac{1}{3} \cdot B \cdot h$

► Surface area: $A = B + L$

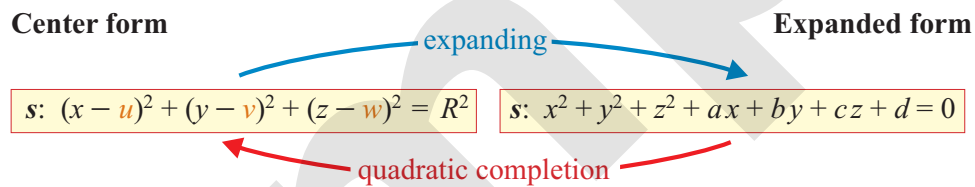
<p>Right, square pyramid</p> <p>a : Side length h : Height s : Slant edge</p> <p>► $V = \frac{1}{3} a^2 \cdot h$</p> <p>► $A = a^2 + L$</p> <p>► $s = \sqrt{h^2 + \frac{a^2}{2}}$</p>	<p>Right circular cone</p> <p>α : Aperture angle h : Height s : Slant edge r : Radius</p> <p>► $V = \frac{1}{3} \pi r^2 \cdot h$</p> <p>► $A = \pi r^2 + \pi r s, \quad L = \pi r s$</p> <p>► $s = \sqrt{h^2 + r^2}$</p>	<p>Frustum of { pyramid, cone</p> <p>► $V_I = \frac{h}{3} (B + \sqrt{BT} + T)$</p> <p>► $V_{II} = \frac{\pi h}{3} (r_1^2 + r_1 r_2 + r_2^2)$</p> <p>► $L_{II} = \pi \cdot s \cdot (r_1 + r_2)$</p>
--	---	--

4.3 Sphere



- Volume:** $V = \frac{4}{3} \pi \cdot R^3$
- ▶ **Cap:** $V = \frac{1}{3} \pi \cdot h_1^2 \cdot (3R - h_1)$
 - ▶ **Zone:** $V = \frac{1}{6} \pi \cdot h_2 \cdot (3r_1^2 + 3r_2^2 + h_2^2)$
 - ▶ **Sector:** $V = \frac{2}{3} \pi R^2 \cdot h_3$
- Surface area:** $A = 4\pi \cdot R^2$
- ▶ **Cap:** $L = 2\pi R \cdot h_1$ (lateral area)
 - ▶ **Zone:** $L = 2\pi R \cdot h_2$ (lateral area)
 - ▶ **Sector:** $A = 2\pi R \cdot h_3 + \pi R \sqrt{2Rh_3 - h_3^2}$

▶ Equation of a sphere s with center $M(u / v / w)$ and radius R :



▶ **Tangent plane t** to a sphere s at a point $P_0(x_0 / y_0 / z_0)$:

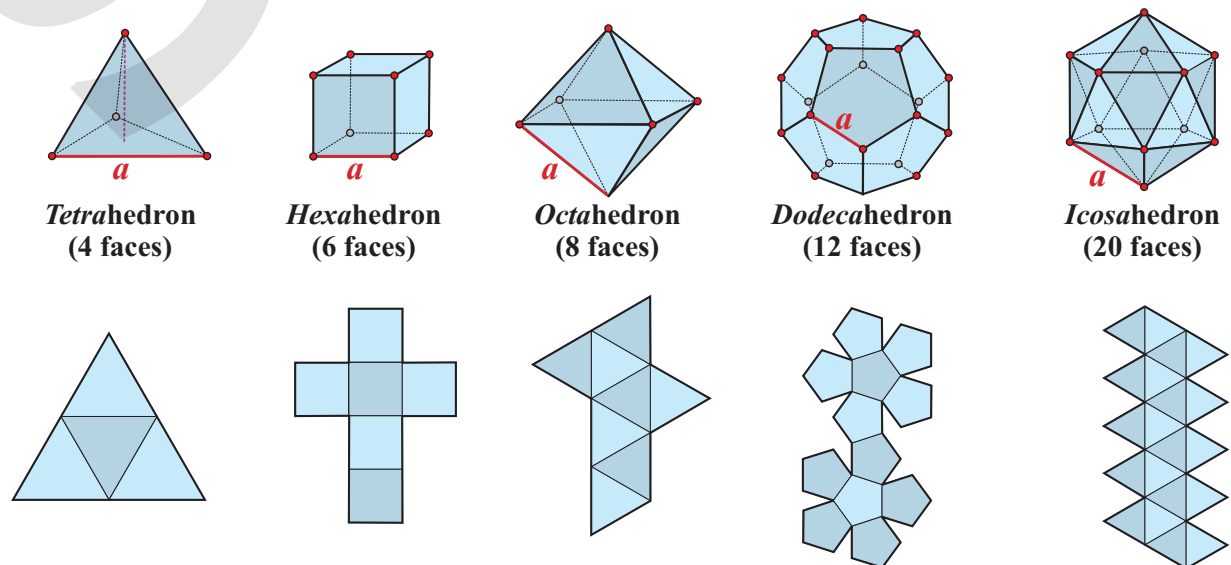
$t: (x - u) \cdot (x_0 - u) + (y - v) \cdot (y_0 - v) + (z - w) \cdot (z_0 - w) = R^2$

 (see planes on p. 35)

4.4 Polyhedra, Platonic Solids

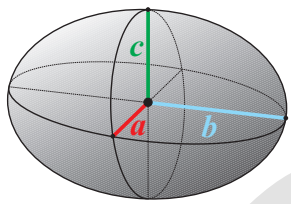
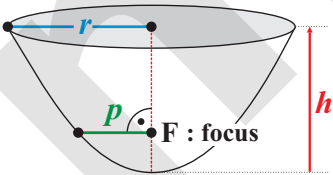
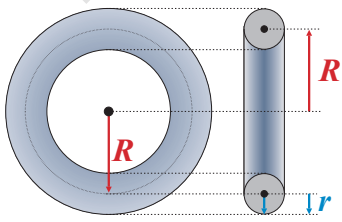
Euler's polyhedron theorem: $V + F = E + 2$ with $\begin{cases} V : \text{number of vertices,} \\ F : \text{number of faces,} \\ E : \text{number of edges.} \end{cases}$

The Platonic Solids: 5 regular convex solids (all equal edges and equal angles)

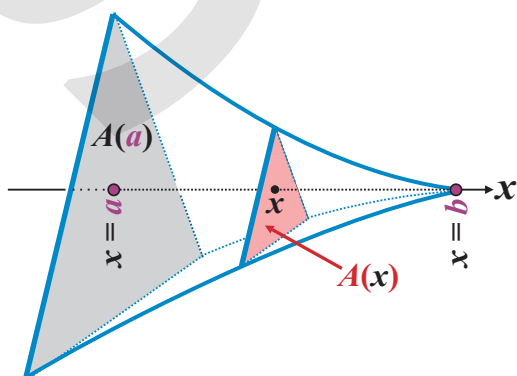


	Volume V	Surface area A	Radius R of the circumsphere	Radius r of the insphere
Tetra-hedron	$\frac{\sqrt{2}}{12} a^3$	$\sqrt{3} a^2$	$\frac{\sqrt{6}}{4} a$	$\frac{\sqrt{6}}{12} a$
Hexa-hedron	a^3	$6 a^2$	$\frac{\sqrt{3}}{2} a$	$\frac{1}{2} a$
Octa-hedron	$\frac{\sqrt{2}}{3} a^3$	$2\sqrt{3} a^2$	$\frac{\sqrt{2}}{2} a$	$\frac{\sqrt{6}}{6} a$
Dodeca-hedron	$\frac{15+7\sqrt{5}}{4} a^3$	$3\sqrt{5(5+2\sqrt{5})} a^2$	$\frac{(1+\sqrt{5})\sqrt{3}}{4} a$	$\frac{\sqrt{10+4.4\sqrt{5}}}{4} a$
Icosa-hedron	$\frac{5(3+\sqrt{5})}{12} a^3$	$5\sqrt{3} a^2$	$\frac{\sqrt{2(5+\sqrt{5})}}{4} a$	$\frac{(3+\sqrt{5})\sqrt{3}}{12} a$

4.5 Solids with Curved Surface

Ellipsoid	Paraboloid	Torus
 <p>▶ $V = \frac{4}{3} \pi \cdot a \cdot b \cdot c$</p>	 <p>▶ $V = \frac{1}{2} \pi \cdot r^2 \cdot h = \pi \cdot p \cdot h^2$</p>	 <p>▶ $V = 2\pi^2 \cdot r^2 \cdot R$</p> <p>▶ $A = 4\pi^2 \cdot r \cdot R$</p>

4.6 Volume of a Solid using Integral Calculus



- $V = \int_a^b A(x) dx$

Cross-section area $A(x) \perp x$ -Axis.

- Solids of revolution: Volume of a solid obtained by the graph of a function $f(x)$ rotating about the x -axis:

$$V_x = \pi \cdot \int_a^b (f(x))^2 dx \quad (\text{see p. 31})$$

5 Functions

Definition: A function $f : \mathbb{D} \rightarrow \mathbb{W}$ is a **mapping** from one set \mathbb{D} (**domain**) to another set \mathbb{W} (**range**) so that **each** element $x \in \mathbb{D}$ is assigned a **unique** element $y \in \mathbb{W}$:

$$f : x \mapsto y = f(x)$$

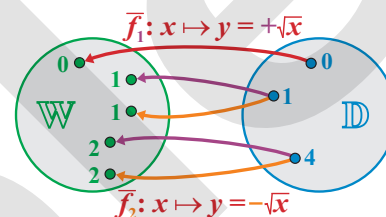
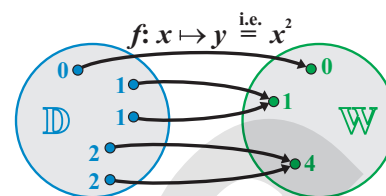
Inverse function: $\bar{f} : \mathbb{W} \rightarrow \mathbb{D}$ reverses the function f :

$$\bar{f}(f(x)) = x \quad \text{and} \quad f(\bar{f}(y)) = y$$

Only one-to-one mappings have inverse functions. In order to make a function f invertible, its domain has to be restricted such that f becomes monotonic.

Finding the inverse function:

- ▶ *Graphically:* Reflect the graph in the first angle bisector $y = x$.
- ▶ *Algebraically:* Solve $y = f(x)$ for x .
Then, interchange x and y .



Domain: Set of all allowed x -values:

- $\frac{U(x)}{V(x)} \Rightarrow V(x) \neq 0$
- $\sqrt{g(x)} \Rightarrow g(x) \geq 0$
- $\log_a(g(x)) \Rightarrow g(x) > 0$

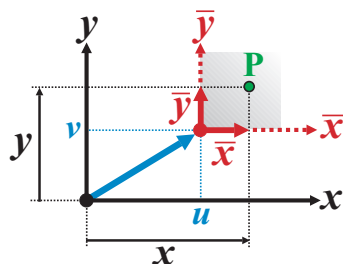
Table of functions and their inverse functions:

Function	$y = f(x)$	\mathbb{D}_f	\mathbb{W}_f	$y = \bar{f}(x)$
Reciprocal	$\frac{1}{x} = x^{-1}$	$\mathbb{R} \setminus \{0\}$	$\mathbb{R} \setminus \{0\}$	$\frac{1}{x} = x^{-1}$
Square	x^2	\mathbb{R}	$y \geq 0$	\sqrt{x}
Power	x^n	\mathbb{R}	if n even: $y \geq 0$ if n odd: \mathbb{R}	$\sqrt[n]{x}$
Sine	$\sin(x)$	\mathbb{R}	$[-1, 1]$	$\arcsin(x)$
Cosine	$\cos(x)$	\mathbb{R}	$[-1, 1]$	$\arccos(x)$
Tangent	$\tan(x)$	$\mathbb{R} \setminus \{(n + \frac{1}{2})\pi, n \in \mathbb{Z}\}$	\mathbb{R}	$\arctan(x)$
Exponential	a^x	\mathbb{R}	$y > 0$	$\log_a(x)$

5.1 Translation, Rotation of the Coordinate System

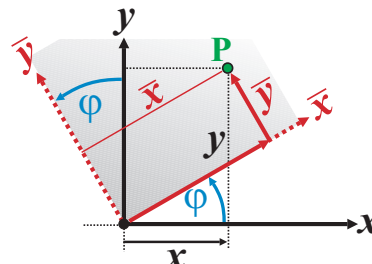
Translation of $\begin{pmatrix} u \\ v \end{pmatrix}$:

$$\begin{aligned} \bar{x} &= x - u \\ \bar{y} &= y - v \end{aligned}$$

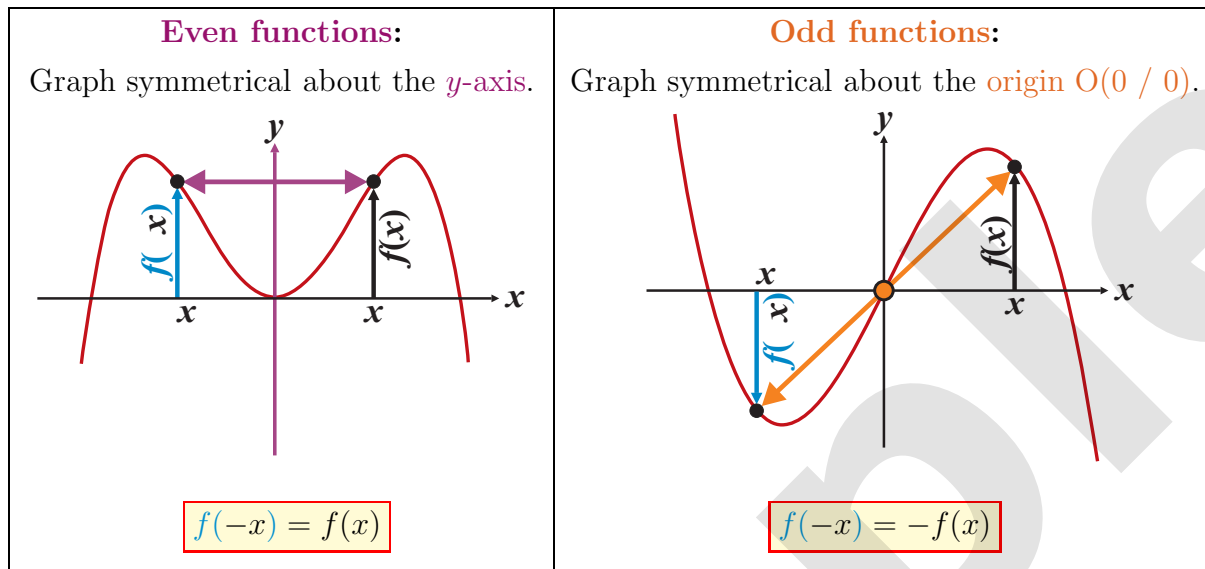


Rotation by φ :

$$\begin{aligned} \bar{x} &= x \cos(\varphi) + y \sin(\varphi) \\ \bar{y} &= -x \sin(\varphi) + y \cos(\varphi) \end{aligned}$$



5.2 Symmetry

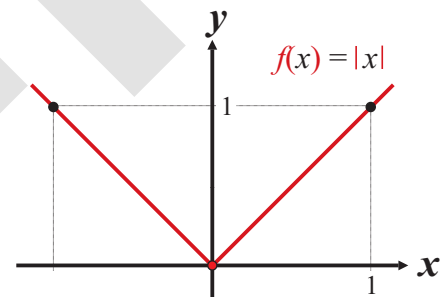


5.3 Absolute Value

$$|x| = \sqrt{x^2} = \begin{cases} x & \text{if } x \geq 0 \\ -x & \text{if } x < 0 \end{cases}$$

„makes x positive“.

- $|x|$ is continuous but not differentiable at $x = 0$.
- $|a \cdot b| = |a| \cdot |b|$ $|\frac{a}{b}| = \frac{|a|}{|b|}$
- $||a| - |b|| \leq |a + b| \leq |a| + |b|$.



5.4 Power Functions

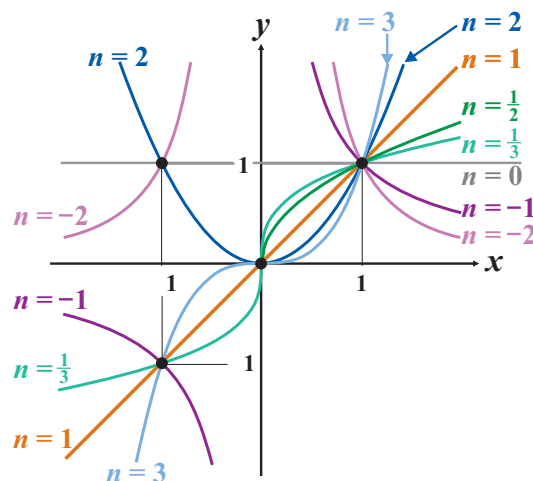
Power function: $f(x) = x^n$ $n \in \mathbb{Q}$.

- $n = 0$ Constant function.
- $0 < n < 1$ Root functions.
- $n = 1$ Linear function.
- $n \in \mathbb{N}; n > 1$ Parabolas of n^{th} order.
- $n \in \mathbb{Z}; n < 0$ Hyperbolas of n^{th} order.

The graph of $f(x) = x^n$ is...

- ...symmetrical about the y -axis if n is even,
- ...symmetrical about the origin if n is odd.

⇒ Derivatives and antiderivatives see p. 29.

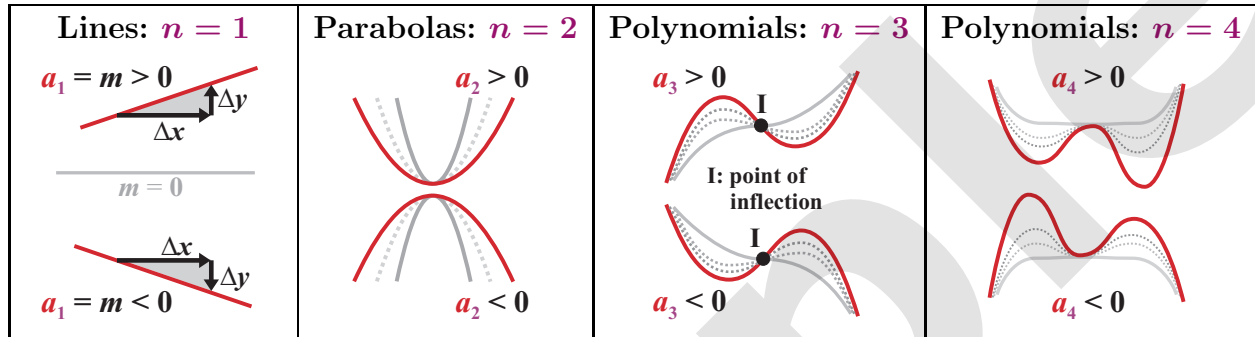


5.5 Polynomial Functions (Parabolas of Degree n)

$$y = f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 = \sum_{k=0}^n a_k x^k \quad \text{with } \begin{cases} n : \text{Degree, order,} \\ a_n \neq 0. \end{cases}$$

$a_n, a_{n-1}, a_{n-2}, \dots, a_1, a_0$ are the **coefficients** of $f(x)$.

Overview of the graphs of polynomial functions:



5.5.1 Linear Functions ($n = 1$): $y = m \cdot x^1 + q$ see p. 34.

► Normal form: $g : y = m \cdot x + q$

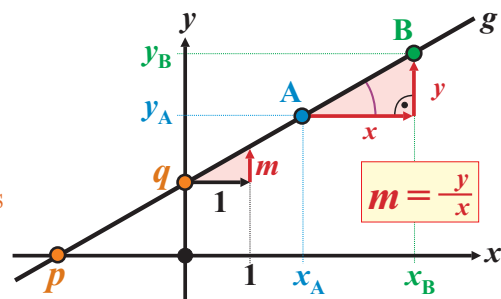
► Point-slope form: $g : y = m \cdot (x - x_A) + y_A$ with $A(x_A / y_A) \in g$.

• **Slope:** $m = \frac{\Delta y}{\Delta x} = \frac{y_B - y_A}{x_B - x_A} = \tan(\alpha)$

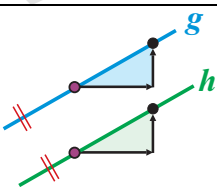
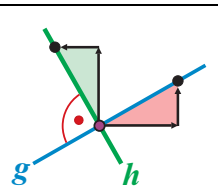
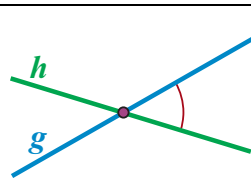
• **y-Intercept:** q .

► Intercept form: $g : \frac{x}{p} + \frac{y}{q} = 1$ with the axis

intercepts $p, q \in \mathbb{R} \setminus \{0\} \cup \{\pm\infty\}$.



► Parallel lines, perpendicular lines, angle of intersection:

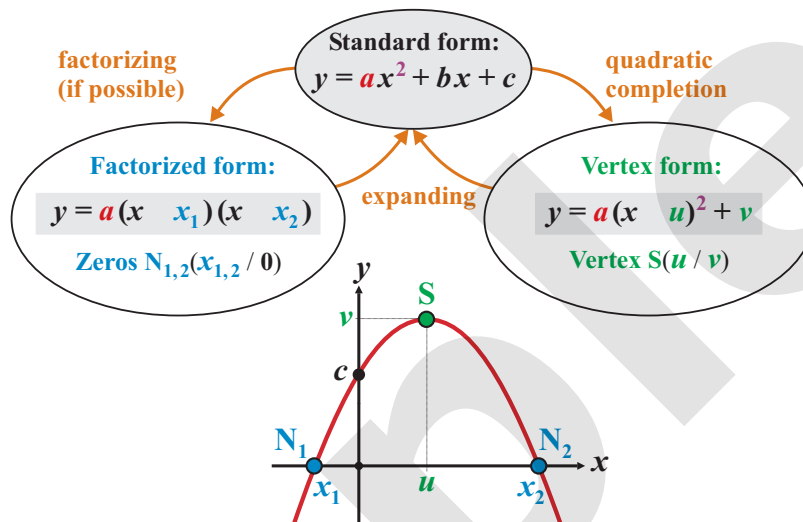
Parallel lines	Perpendicular lines	Angle of intersection $\varphi = \angle(g, h)$
		
$g \parallel h \Leftrightarrow m_g = m_h$	$g \perp h \Leftrightarrow m_h = \frac{-1}{m_g}$	$\tan(\varphi) = \left \frac{m_h - m_g}{1 + m_h \cdot m_g} \right $

► Vector equation and cartesian form on p. 34.

5.5.2 Quadratic Functions (Parabolas, $n = 2$): $y = a \cdot x^2 + b \cdot x + c$

- $a < 0$: Parabola opens downwards (\cap),
- $a > 0$: Parabola opens upwards (\cup),
- $a = 1$: Norm parabola.
- bx : Linear term.
- c : y -Intercept.
- Vertex $S(u / v)$:
 $S(-\frac{b}{2a} / \frac{-b^2 + 4ac}{4a})$.

\Rightarrow Formula for quadratic equations on p. 21.



5.6 Rational Functions

A rational function $f(x)$ is the quotient of two polynomials:

$$f(x) = \frac{U(x)}{V(x)} = \frac{\text{numerator polynomial}}{\text{denominator polynomial}} = \frac{a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0}{b_m x^m + b_{m-1} x^{m-1} + \dots + b_1 x + b_0}$$

Coefficients: $a_n, b_m \neq 0$.

Degree, order of numerator: $n \in \mathbb{N}_0$. Degree, order of denominator: $m \in \mathbb{N} \setminus \{0\}$.

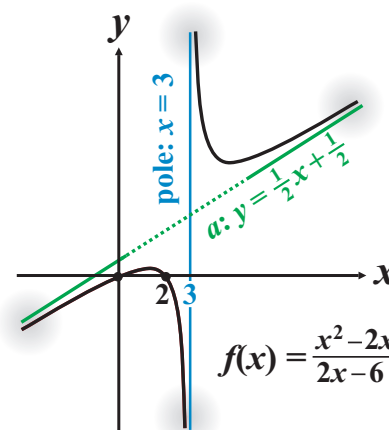
Properties:

► **Vertical asymptotes (poles):** x_0 is called pole of f if
 $y = \lim_{x \rightarrow x_0} f(x) = \pm\infty$ (non-removable division by zero).

► **Horizontal or slant asymptote:**

Approaching function $a(x)$ for $x \rightarrow \pm\infty$. Three cases:

- $n < m$: $\lim_{x \rightarrow \pm\infty} f(x) = 0 \Rightarrow a : y = 0$
- $n = m$: $\lim_{x \rightarrow \pm\infty} f(x) = \frac{a_n}{b_m} \Rightarrow a : y = \frac{a_n}{b_m}$
- $n > m$: $\lim_{x \rightarrow \pm\infty} f(x) = \pm\infty \Rightarrow$ split



$$f(x) = \frac{U(x)}{V(x)} = a(x) + \frac{u(x)}{V(x)} \quad \text{with} \quad \lim_{x \rightarrow \pm\infty} \frac{u(x)}{V(x)} = 0$$

division = long division algorithm.

\Rightarrow For $n = m + 1$, $a(x)$ is a slant, linear asymptote.

$\Rightarrow a(x)$: Polynomial of degree $(n - m)$.

\Rightarrow Limits on p. 25.

5.7 Exponential and Logarithmic Functions

► **Exponential functions:** $y = f(x) = a^x$ $a > 0, x \in \mathbb{R}$.

• **Euler's number:** $e = \lim_{n \rightarrow \infty} \left(1 + \frac{1}{n}\right)^n \approx 2.718\dots$

• Processes of exponential growth respectively decay:

$$N(t) = N_0 \cdot a^t \quad \text{or} \quad N(t) = N_0 \cdot e^{k \cdot t} \quad \text{where:}$$

t : Time.

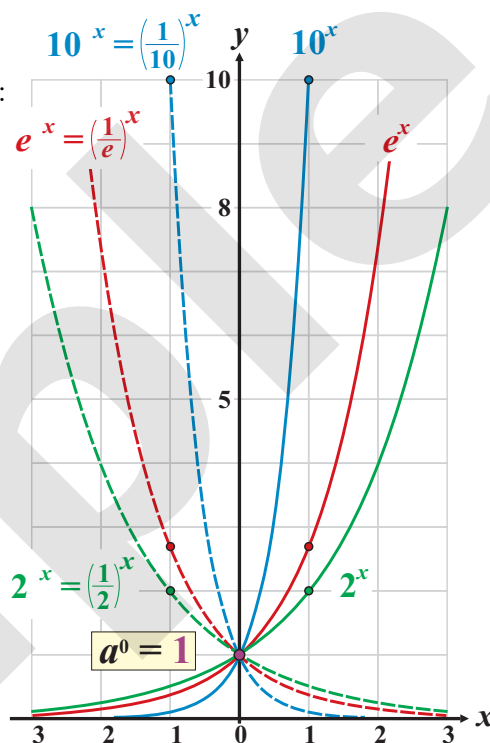
N_0 : Initial population at $t = 0$.

$N(t)$: Population at time t .

$a = e^k$: Growth factor: $a = 1 + \frac{p}{100}$ with

p : $\left\{ \begin{array}{l} \text{growth} \quad (p > 0) \\ \text{decay} \quad (p < 0) \end{array} \right\}$ in %

per time unit.



⇒ Power and logarithm laws on p. 5.

⇒ Derivatives and antiderivatives on p. 29.

⇒ Limits on p. 25.

► **Logarithmic functions:** $\bar{f}(x) = \log_a(x)$ $x > 0, a > 0; a \neq 1$.

$\bar{f}(x) = \log_a(x)$ are inverse functions of $f(x) = a^x$:

• **Common logarithm:**

$$\bar{f}(x) = \log_{10}(x) = \log(x)$$

$$\log(10^x) = x, \quad 10^{\log(x)} = x \quad (x > 0)$$

• **Natural logarithm:**

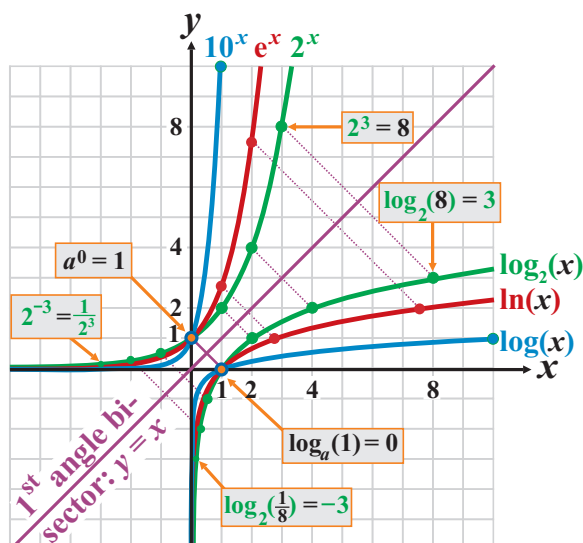
$$\bar{f}(x) = \log_e(x) = \ln(x)$$

$$\ln(e^x) = x, \quad e^{\ln(x)} = x \quad (x > 0)$$

• **Binary logarithm:**

$$\bar{f}(x) = \log_2(x) = \text{lb}(x)$$

$$\log_2(2^x) = x, \quad 2^{\log_2(x)} = x \quad (x > 0)$$



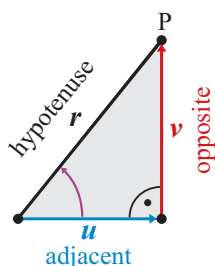
⇒ Power and logarithm laws on p. 5.

⇒ Derivatives and antiderivatives on p. 29.

5.8 Trigonometric Functions

► **Definition:** (see p. 6)

Right-angled triangle: $0^\circ < \alpha < 90^\circ$.

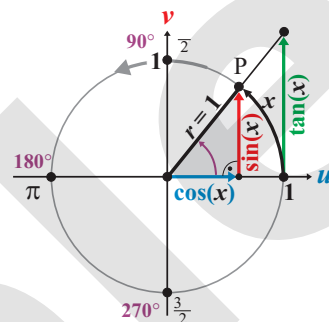


$$\sin(\alpha) = \frac{v}{r} = \frac{\text{opposite}}{\text{hypotenuse}}$$

$$\cos(\alpha) = \frac{u}{r} = \frac{\text{adjacent}}{\text{hypotenuse}}$$

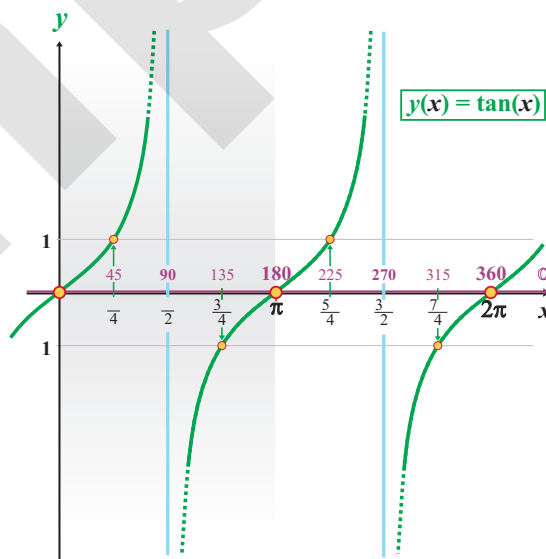
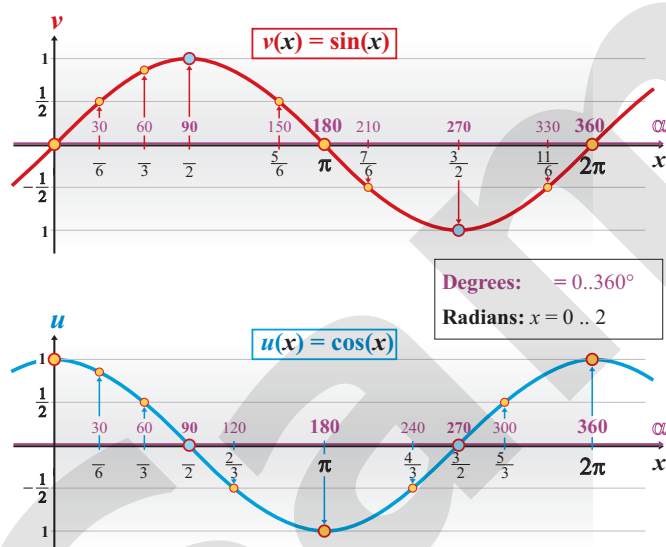
$$\tan(\alpha) = \frac{v}{u} = \frac{\text{opposite}}{\text{adjacent}} = \frac{\sin(\alpha)}{\cos(\alpha)}$$

Unit circle: $x, \alpha \in \mathbb{R}$.



► **Radians:** $x = \alpha \cdot \frac{\pi}{180^\circ}$ { Length of the arc in the unit circle corresponding to the central angle α .

► **Graphs:**



► **Properties and particular values:**

	$0^\circ \doteq 0$	$30^\circ \doteq \frac{\pi}{6}$	$45^\circ \doteq \frac{\pi}{4}$	$60^\circ \doteq \frac{\pi}{3}$	$90^\circ \doteq \frac{\pi}{2}$	Periodicity	Symmetry
$\sin(x)$	0	$\frac{1}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{3}}{2}$	1	$360^\circ \doteq 2\pi$ $\sin(x + 2\pi n) = \sin(x)$	$\sin(\pi - x) = \sin(x)$ $\sin(-x) = -\sin(x)$
$\cos(x)$	1	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{1}{2}$	0	$360^\circ \doteq 2\pi$ $\cos(x + 2\pi n) = \cos(x)$	$\cos(2\pi - x) = \cos(x)$ $\cos(-x) = \cos(x)$
$\tan(x)$	0	$\frac{\sqrt{3}}{3}$	1	$\sqrt{3}$	$(\pm\infty)$	$180^\circ \doteq \pi$ $\tan(x + \pi n) = \tan(x)$	$\tan(-x) = -\tan(x)$

► **Domain:** $\mathbb{D}_{\sin} = \mathbb{D}_{\cos} = \mathbb{R}$ $\mathbb{D}_{\tan} = \mathbb{R} \setminus \{(\frac{\pi}{2} + n\pi), n \in \mathbb{Z}\}$.

► **Range:** $\mathbb{W}_{\sin} = \mathbb{W}_{\cos} = [-1, 1]$ $\mathbb{W}_{\tan} = \mathbb{R}$.

► **Inverse functions:** $\begin{cases} \arcsin(x) & \text{sometimes denoted } \sin^{-1}(x), \\ \arccos(x) & \text{sometimes denoted } \cos^{-1}(x), \\ \arctan(x) & \text{sometimes denoted } \tan^{-1}(x). \end{cases}$ Derivatives and anti-derivatives on p. 29.

► Identities and Properties of Trigonometric Functions:

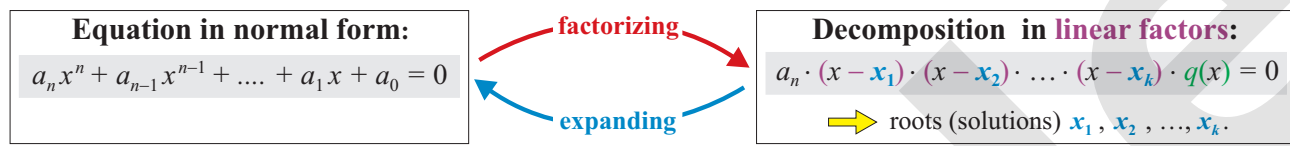
$\tan(x) = \frac{\sin(x)}{\cos(x)}$	$\sin^2(x) + \cos^2(x) = 1$	$\frac{1}{\cos^2(x)} = 1 + \tan^2(x)$
$\sin(-x) = -\sin(x)$	$\cos(-x) = \cos(x)$	$\tan(-x) = -\tan(x)$
$\sin(\pi - x) = \sin(x)$	$\cos(\pi - x) = -\cos(x)$	$\tan(\pi - x) = -\tan(x)$
$\sin\left(\frac{\pi}{2} \pm x\right) = \cos(x)$	$\cos\left(\frac{\pi}{2} \pm x\right) = \mp \sin(x)$	$\tan\left(\frac{\pi}{2} \pm x\right) = \mp \frac{1}{\tan(x)}$
$\sin(2x) = 2 \sin(x) \cos(x)$	$\cos(2x) = \begin{cases} 2 \cos^2(x) - 1 \\ \cos^2(x) - \sin^2(x) \\ 1 - 2 \sin^2(x) \end{cases}$	$\tan(2x) = \frac{2 \tan(x)}{1 - \tan^2(x)}$
$\sin(3x) = 3 \sin(x) - 4 \sin^3(x)$	$\cos(3x) = 4 \cos^3(x) - 3 \cos(x)$	$\tan(3x) = \frac{3 \tan(x) - \tan^3(x)}{1 - 3 \tan^2(x)}$
$\sin^2\left(\frac{x}{2}\right) = \frac{1 - \cos(x)}{2}$	$\cos^2\left(\frac{x}{2}\right) = \frac{1 + \cos(x)}{2}$	$\tan^2\left(\frac{x}{2}\right) = \frac{1 - \cos(x)}{1 + \cos(x)}$
$\sin(x \pm y) = \sin(x) \cdot \cos(y) \pm \cos(x) \cdot \sin(y)$	$\tan(x + y) = \frac{\tan(x) + \tan(y)}{1 - \tan(x) \cdot \tan(y)}$	
$\cos(x \pm y) = \cos(x) \cdot \cos(y) \mp \sin(x) \cdot \sin(y)$	$\tan(x - y) = \frac{\tan(x) - \tan(y)}{1 + \tan(x) \cdot \tan(y)}$	
$\sin(x) + \sin(y) = 2 \cdot \sin\left(\frac{x+y}{2}\right) \cdot \cos\left(\frac{x-y}{2}\right)$	$\sin(x) - \sin(y) = 2 \cdot \cos\left(\frac{x+y}{2}\right) \cdot \sin\left(\frac{x-y}{2}\right)$	
$\cos(x) + \cos(y) = 2 \cdot \cos\left(\frac{x+y}{2}\right) \cdot \cos\left(\frac{x-y}{2}\right)$	$\cos(x) - \cos(y) = -2 \cdot \sin\left(\frac{x+y}{2}\right) \cdot \sin\left(\frac{x-y}{2}\right)$	

⇒ Derivatives and antiderivatives see p. 29.

6 Equations

6.1 Fundamental Theorem of Algebra

Every polynomial of degree n can be written as a product of $k \leq n$ linear factors and irreducible quadratic factors $q(x) \neq 0$ for all $x \in \mathbb{R}$:



6.2 Quadratic Equations

$$a \cdot x^2 + b \cdot x + c = 0 \quad a, b, c \in \mathbb{R}, \quad a \neq 0.$$

Discriminant: $D = b^2 - 4 \cdot a \cdot c$

Solutions: $x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4 \cdot a \cdot c}}{2 \cdot a} \quad D \geq 0.$

Viète's formulas:

Product of solutions: $x_1 \cdot x_2 = \frac{c}{a}$

Sum of solutions: $x_1 + x_2 = -\frac{b}{a}$

⇒ Quadratic functions on p. 17.

6.3 Polynomial Equations of 3rd and Higher Degree

$$a \cdot x^3 + b \cdot x^2 + c \cdot x + d = 0 \quad a, b, c, d \in \mathbb{R}, \quad a \neq 0.$$

Method: Normalize to $a = 1$ (division by $a \neq 0$), that is $x^3 + b' \cdot x^2 + c' \cdot x + d' = 0$.

If there is an integer solution x_1 , it must be a divisor of d' . Find solution x_1 by trying the divisors of d' . Then divide the equation by $(x - x_1)$ and find further solutions.

6.4 Numerical Methods to Calculate Zeros

To calculate a zero $N(x_N / 0)$ of a function $f(x)$, start with a guess x_1 . Then, set up a recursive sequence x_1, x_2, x_3, \dots with limit x_N .

► Secant method:

Choose $P(a / f(a))$ and $Q(b / f(b))$ with $f(a) \cdot f(b) < 0$.

Using $x_1 = a$ as initial value, calculate:

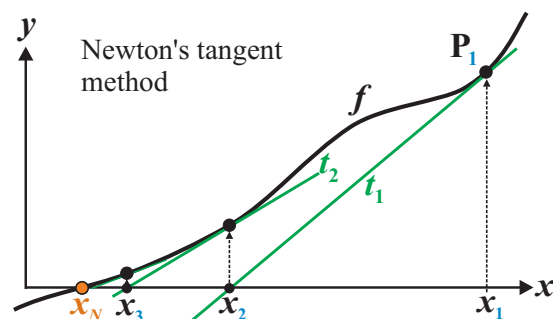
$$x_{n+1} = x_n - f(x_n) \frac{b - x_n}{f(b) - f(x_n)} \xrightarrow{n \rightarrow \infty} x_N$$

► Newton's tangent method:

Choose $P_1(x_1 / f(x_1))$ with $f'(x_1) \neq 0$. Then:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \xrightarrow{n \rightarrow \infty} x_N$$

The sequence is not always convergent.



7 Matrices, Systems of Linear Equations

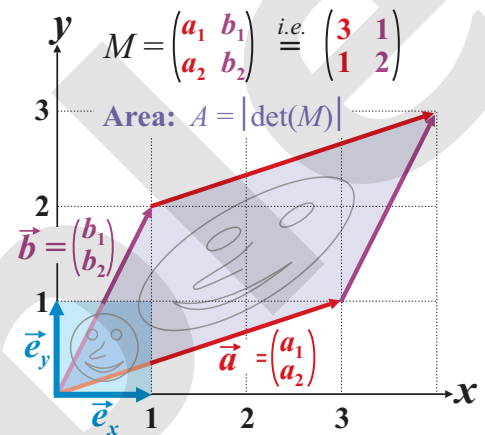
7.1 Simultaneous Linear Equations, 2×2 Matrices

$$\begin{cases} a_1x + b_1y = c_1 \\ a_2x + b_2y = c_2 \end{cases} \Rightarrow \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad \text{briefly: } \boxed{M \cdot \vec{x} = \vec{c}}$$

- Multiplying the matrix M from the left by its inverse M^{-1} , solves the equation $M \cdot \vec{x} = \vec{c}$ for \vec{x} :

$$\boxed{\vec{x} = M^{-1} \cdot \vec{c}} \quad (\text{if } M^{-1} \text{ exists}).$$

- The Matrix $M = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}$ represents a linear transformation from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$:
Each vector $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$ is assigned the vector $\vec{c} = \begin{pmatrix} c_x \\ c_y \end{pmatrix} = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$.



- The columns \vec{a} , \vec{b} of the matrix M are the images of the Cartesian unit vectors \vec{e}_x and \vec{e}_y under the linear transformation M .

7.2 Operations and Properties of Matrices

► Identity matrices: $I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$, $I_n = \begin{pmatrix} 1 & \cdots & 0 \\ \vdots & 1 & \\ 0 & \cdots & \ddots & \\ & & & 1 \end{pmatrix}$

- $M \cdot I_n = I_n \cdot M = M$

► Addition: $\begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \pm \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix} = \begin{pmatrix} a_1 \pm u_1 & b_1 \pm v_1 \\ a_2 \pm u_2 & b_2 \pm v_2 \end{pmatrix}$

- $M_1 + M_2 = M_2 + M_1$

- $(M_1 + M_2) + M_3 = M_1 + (M_2 + M_3)$

► Multiplication by a scalar (real number): $k \cdot \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} = \begin{pmatrix} k a_1 & k b_1 \\ k a_2 & k b_2 \end{pmatrix}$; $k \in \mathbb{R}$.

► Multiplication by a vector: $\begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a_1x + b_1y \\ a_2x + b_2y \end{pmatrix}$

► Product of two matrices: $\begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \cdot \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix} = \begin{pmatrix} a_1u_1 + b_1u_2 & a_1v_1 + b_1v_2 \\ a_2u_1 + b_2u_2 & a_2v_1 + b_2v_2 \end{pmatrix}$

- $M_1 \cdot M_2 \neq M_2 \cdot M_1$

- $(M_1 \cdot M_2) \cdot M_3 = M_1 \cdot (M_2 \cdot M_3)$

► **Transposition:** $M^T = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}^T = \begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix}$ $M^T = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix}^T = \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix}$

- $(M_1 + M_2)^T = M_1^T + M_2^T$
- $(M_1 \cdot M_2)^T = M_2^T \cdot M_1^T$
- $(M^T)^T = M$

► **Inverse matrix:** $M \cdot M^{-1} = M^{-1} \cdot M = I_n$ • $(M_1 \cdot M_2)^{-1} = M_2^{-1} \cdot M_1^{-1}$

$M^{-1} = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}^{-1} = \frac{1}{\det(M)} \begin{pmatrix} b_2 & -b_1 \\ -a_2 & a_1 \end{pmatrix}$ if $\det(M) \neq 0$. • $(M^{-1})^{-1} = M$

In general: $[M \mid E_n] \xrightarrow{\text{Gauss}} [E_n \mid M^{-1}]$. • $(M^{-1})^T = (M^T)^{-1}$

► **Determinant:** $\det \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} = a_1 \cdot b_2 - a_2 \cdot b_1$

$\det \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix} = a_1 \cdot \det \begin{pmatrix} b_2 & c_2 \\ b_3 & c_3 \end{pmatrix} - b_1 \cdot \det \begin{pmatrix} a_2 & c_2 \\ a_3 & c_3 \end{pmatrix} + c_1 \cdot \det \begin{pmatrix} a_2 & b_2 \\ a_3 & b_3 \end{pmatrix}$

- $\det(A \cdot B) = \det(A) \cdot \det(B)$
- $\det(I_n) = 1$
- $\det(A^T) = \det(A)$ $\det(A^{-1}) = \frac{1}{\det(A)}$
- $\det(k \cdot A) = k^n \cdot \det(A)$

► **Rank:** Number of linearly independent rows (or columns) of a matrix. M is called a...

- *regular* $n \times n$ matrix, if: $\det(M) \neq 0 \Leftrightarrow \text{rank}(M) = n \Leftrightarrow M^{-1}$ exists.
- *singular* $n \times n$ matrix, if: $\det(M) = 0 \Leftrightarrow \text{rank}(M) < n \Leftrightarrow M^{-1}$ does not exist.

► **Orthogonal matrices:** $M \cdot M^T = M^T \cdot M = I$ respectively $M^T = M^{-1}$ holds.

► **Eigenvectors, eigenvalues:** A vector \vec{v} is called **eigenvector** of M to the **eigenvalue** λ , if $M \cdot \vec{v} = \lambda \cdot \vec{v}$ holds. The linear function M leaves the orientation of \vec{v} **unchanged**.

[i] Calculate the **eigenvalues** λ : $\det(M - \lambda \cdot E_n) = 0 \Rightarrow \lambda_1, \lambda_2, \dots$

[ii] Solve for the **eigenvectors** \vec{v}_k : $(M - \lambda_k \cdot E_n) \cdot \vec{v}_k = 0 \Rightarrow \vec{v}_1, \vec{v}_2, \dots$

► **Elementary matrix operations (Gaussian algorithm):**

- | | |
|--|---|
| <ul style="list-style-type: none"> • Multiplying a row by a real number $k \neq 0$. • Adding a row to another row. • Switching two rows of a matrix. | <p>Solving systems of linear equations:</p> <ul style="list-style-type: none"> • Write simultaneous linear equations as a matrix $[M \mid \vec{c}]$. • Transform M to unity matrix using the Gaussian algorithm. |
|--|---|

► **Special matrices:**

$\begin{pmatrix} \cos(\alpha) & -\sin(\alpha) \\ \sin(\alpha) & \cos(\alpha) \end{pmatrix}$ rotates $\vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$ by the angle α anticlockwise about $O(0 / 0)$.

Reflection of $\vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$ about the... x -axis: $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ y -axis: $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$.

8 Sequences and Series

Definition: A sequence is a function $u : \mathbb{N} \rightarrow \mathbb{R}$, $n \mapsto u_n$. (See. p. 14.) Notation:

- **Explicit formula:** $u_n = \{\text{formula in } n \text{ only}\}$.
- **Recurrence formula:** $u_{n+1} = \{\text{formula in } u_n, u_{n-1}, \dots\}$ with given initial value u_1 .

A **series** s_1, s_2, s_3, \dots is the sequence of **partial sums** of a given sequence $\{u_n\}_{n \in \mathbb{N}}$:

$$s_1 = u_1 \xrightarrow{+u_2} s_2 = u_1 + u_2 \xrightarrow{+u_3} s_3 = u_1 + u_2 + u_3 \dots \quad s_n = \sum_{k=1}^n u_k$$

8.1 Arithmetic Sequences and Series

Constant **difference** $d = u_2 - u_1$ } $u_1 \xrightarrow{+d} u_2 \xrightarrow{+d} u_3 \xrightarrow{+d} \dots$
 between consecutive elements:

	Recurrence	Explicit formula
Sequence	$u_{n+1} = u_n + d$	$u_n = u_1 + (n-1) \cdot d$
Series	$s_{n+1} = s_n + u_{n+1}$	$s_n = \frac{n}{2} \cdot (u_1 + u_n) = \frac{n}{2} \cdot (2u_1 + (n-1) \cdot d)$

8.2 Geometric Sequences and Series

Constant **ratio (quotient)** $r = \frac{u_2}{u_1}$ } $u_1 \xrightarrow{\cdot r} u_2 \xrightarrow{\cdot r} u_3 \xrightarrow{\cdot r} \dots$
 between consecutive elements:

	Recurrence	Explicit formula
Sequence	$u_{n+1} = u_n \cdot r$	$u_n = u_1 \cdot r^{n-1}$
Series	$s_{n+1} = s_n + u_{n+1}$	$s_n = u_1 \cdot \frac{1 - r^n}{1 - r}$ $r \neq 1$, $s_n = n \cdot u_1$ if $r = 1$. $s = \lim_{n \rightarrow \infty} s_n = \frac{u_1}{1 - r}$ if $ r < 1$. Limits on p. 25.

8.3 Other Series

$$\sum_{k=1}^n \frac{1}{k^2} = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \dots + \frac{1}{n^2} \xrightarrow{n \rightarrow \infty} \frac{\pi^2}{6}$$

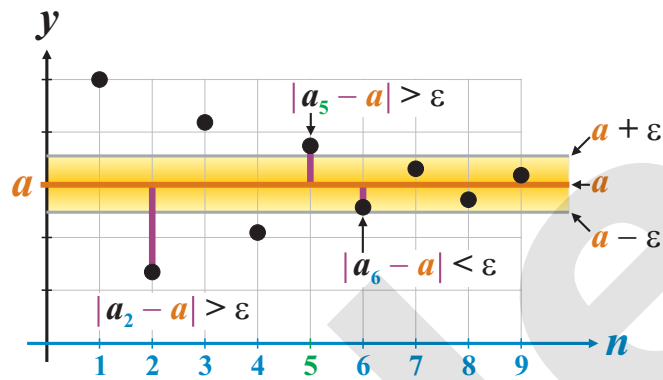
$$\sum_{k=1}^n \frac{1}{k} = \frac{1}{1} + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} \xrightarrow{n \rightarrow \infty} \infty \quad (\text{Harmonic series})$$

$$\sum_{k=1}^n k = \frac{1}{2} \cdot n \cdot (n+1) \quad \sum_{k=1}^n k^2 = \frac{n}{6} \cdot (n+1) \cdot (2n+1) \quad \sum_{k=1}^n k^3 = \left(\frac{1}{2} \cdot n \cdot (n+1)\right)^2$$

8.4 Limits

A sequence is called **convergent** with **limit** $a = \lim_{n \rightarrow \infty} a_n$, if for **any** arbitrarily small number $\varepsilon > 0$ there is an **index** $N \in \mathbb{N}$, such that $|a_n - a| < \varepsilon$ holds for all $n > N$.

For arbitrarily large n , the **distance** between a_n and a tends to 0.



- A **limit** is always **unique** and **finite**.
- Sequences **without limit** (or such with $\lim_{n \rightarrow \infty} a_n = \pm\infty$) are called **divergent**.
- **Undefined expressions:** $\frac{0}{0}$, $\frac{(\pm\infty)}{(\pm\infty)}$, $0 \cdot (\pm\infty)$ and $\infty - \infty$

► **Limit identities:** Assuming that $a = \lim_{n \rightarrow \infty} a_n$ and $b = \lim_{n \rightarrow \infty} b_n$ exist:

- $\lim_{n \rightarrow \infty} (a_n \pm b_n) = a \pm b$
- $\lim_{n \rightarrow \infty} (c \cdot a_n) = c \cdot a$
- $\lim_{n \rightarrow \infty} (a_n \cdot b_n) = a \cdot b$
- $\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = \frac{a}{b}$ if $b \neq 0$

⇒ Similar identities hold for limits $\lim_{x \rightarrow x_0} f(x)$.

► **Particular limits:**

- $\lim_{n \rightarrow \pm\infty} \frac{1}{n} = 0$
- $\lim_{n \rightarrow \pm\infty} \frac{1}{n} = \pm\infty$
- $\lim_{n \rightarrow \infty} \left(1 + \frac{x}{n}\right)^n = e^x$
- $\lim_{n \rightarrow \infty} \frac{a^n}{n!} = 0$
- $\lim_{x \rightarrow \infty} a^x = \begin{cases} 0, & \text{if } -1 < a < 1 \\ 1, & \text{if } a = 1 \\ \infty, & \text{if } a > 1 \end{cases}$
- $\lim_{x \rightarrow \infty} \frac{a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0}{b_m x^m + b_{m-1} x^{m-1} + \dots + b_1 x + b_0} = \begin{cases} 0, & n < m \\ \frac{a_n}{b_m}, & n = m \\ \pm\infty, & n > m \end{cases}$
- $\lim_{x \rightarrow 0} \frac{e^x - 1}{x} = 1$.

► **Order of convergence (dominance rule):**

Exponential growth is faster

than power growth: $\lim_{x \rightarrow \infty} \frac{x^n}{e^x} = 0$

Power growth is faster than

logarithmic growth: $\lim_{x \rightarrow \infty} \frac{\ln(x)}{x^n} = 0$ $n > 0$.

► **L'Hôpital's rule:** Assume $\lim_{x \rightarrow x_0} f(x) = 0$ (or ∞) **and** $\lim_{x \rightarrow x_0} g(x) = 0$ (or ∞), then:

$$\lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} = \lim_{x \rightarrow x_0} \frac{f'(x)}{g'(x)}$$

Example: $\lim_{x \rightarrow 0} \frac{\sin(x)}{x} = \lim_{x \rightarrow 0} \frac{\cos(x)}{1} = 1$.

8.5 Mean Values

Let x_1, x_2, \dots, x_n be n given values.

Arithmetic mean value	$\bar{x}_A = \frac{x_1 + x_2 + \dots + x_n}{n}$ (see p. 39)
Weighted average value (see expected value, p. 37)	$\bar{x}_A = \frac{p_1 \cdot x_1 + p_2 \cdot x_2 + \dots + p_n \cdot x_n}{p_1 + p_2 + \dots + p_n}$ where p_1, p_2, \dots, p_n are the relative frequencies of the values x_1, x_2, \dots, x_n .
Root mean square value	$\bar{x}_{\text{RMS}} = \sqrt{\frac{x_1^2 + x_2^2 + \dots + x_n^2}{n}}$
Geometric mean value	$\bar{x}_G = \sqrt[n]{x_1 \cdot x_2 \cdot \dots \cdot x_n}$
Harmonic mean value	$\bar{x}_H = n \cdot \left(\frac{1}{x_1} + \frac{1}{x_2} + \dots + \frac{1}{x_n} \right)^{-1}$ $x_k \neq 0$.

Inequalities: $\bar{x}_H \leq \bar{x}_G \leq \bar{x}_A \leq \bar{x}_{\text{RMS}}$ hold, if $x_k \geq 0$ for all $k = 1, 2, \dots, n$.

8.6 Harmonic Section, Golden Ratio

Two lines are in the Golden Ratio Φ if they intersect in

the Harmonic Ratio: $\Phi = \frac{a}{b} = \frac{a+b}{a}$ therefore:

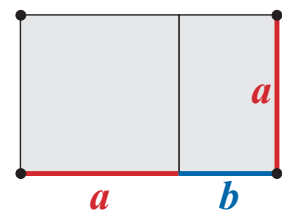
$$\Phi^2 - \Phi - 1 = 0 \Rightarrow \Phi_{1,2} = \frac{1 \pm \sqrt{5}}{2} = \begin{cases} \Phi = 1.618\dots \\ \bar{\Phi} = -0.618\dots \end{cases}$$

Properties:

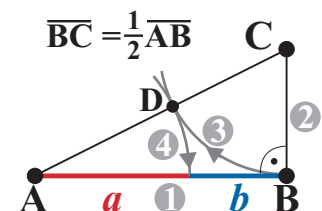
- $\bar{\Phi} = -\frac{1}{\Phi}$
- Φ is irrational and can also be written as:

$$\Phi = \sqrt{1 + \sqrt{1 + \sqrt{1 + \dots}}} \quad \Phi = 1 + \frac{1}{1 + \frac{1}{\dots}}$$

Golden rectangle:



Harmonic section of \overline{AB} :



8.7 Mathematical Induction

Method of mathematical proof for statements \mathbb{A}_n on natural numbers (\mathbb{N}).

(I) **Base clause:** Show that \mathbb{A}_1 is true.

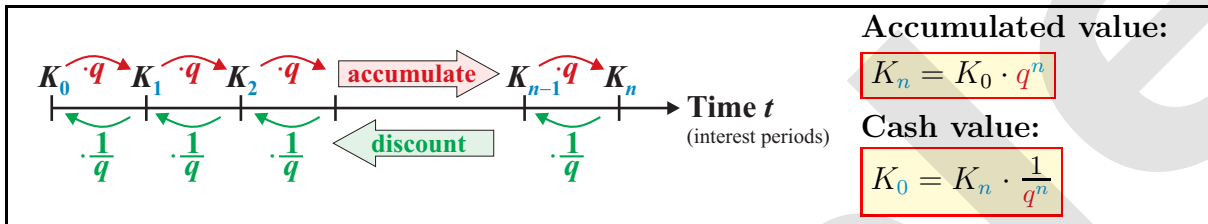
Note: Instead of $n = 1$ a different initial value n_0 can be chosen. The proof holds for all $n \geq n_0$.

(II) **Recursive clause, step from n to $(n + 1)$:** Calculate \mathbb{A}_{n+1} recursively and show that the result coincides with the one calculated directly, that is \mathbb{A}_{n+1} obtained by substituting n by $(n + 1)$ in \mathbb{A}_n .

9 Financial Mathematics

Interest factor: $q = 1 + \frac{p}{100} = 1 + i$ p : Interest (p.a.) in %, $i = \frac{p}{100}$: Interest rate.

► **Capital with compound interest:** Seed capital K_0 , duration n years:



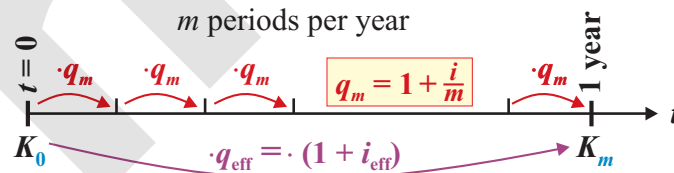
► **Interest for parts of a year:**

Linear:	Compound interest:	Continuous interest:
Capital K_T after T days of simple interest:	m interest periods per year, duration: n years.	Interest is paid continuously:
$K_T = K_0 + K_0 \cdot i \cdot \frac{T}{360}$	$K_{n \cdot m} = K_0 \cdot \left(1 + \frac{i}{m}\right)^{n \cdot m}$	$K_\infty = \lim_{m \rightarrow \infty} K_{n \cdot m} = K_0 \cdot e^{i \cdot n}$

Effective rate of interest:

$$i_{\text{eff}} = \left(1 + \frac{i}{m}\right)^m - 1$$

$$q_m = \sqrt[m]{q_{\text{eff}}}$$



► **Rent computation (annuities):** n rents R are paid to an initial capital K_0 :

Rent R paid in advance:		Rent R paid in arrear:	
<p>Cash value: B_0 Accumulated: E_n</p>		<p>Cash value: B_0 Accumulated: E_n</p>	
Cash value $B_0 =$	Accumulated value $E_n =$	Cash value $B_0 =$	Accumulated value $E_n =$
$K_0 + \frac{R}{q^{n-1}} \frac{q^n - 1}{q - 1}$	$K_0 q^n + R q \frac{q^n - 1}{q - 1}$	$K_0 + \frac{R}{q^n} \frac{q^n - 1}{q - 1}$	$K_0 q^n + R \frac{q^n - 1}{q - 1}$

⇒ The rent R is also called amortization rate or annuity.

► **Derivatives in economics:**

Marginal function:

$$f'(x) = \frac{df}{dx}$$

Growth rate:

$$r(t) = \frac{f'(t)}{f(t)} = \frac{d}{dt} \ln(f(t))$$

Elasticity:

$$\varepsilon_f(x) = x \cdot \frac{f'(x)}{f(x)}$$

10 Differential Calculus

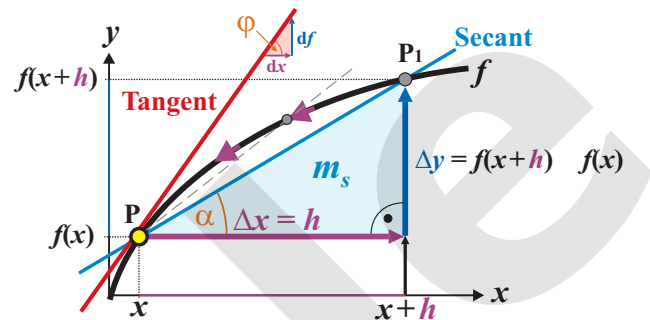
- **Slope of the secant, difference quotient:**
Average rate of change (slope) of $f(x)$ in the interval $[x, x+h]$:

$$m_s = \frac{\Delta y}{\Delta x} = \frac{f(x+h) - f(x)}{h} = \tan(\alpha)$$

- **Slope of the tangent, differential quotient:**
Instantaneous rate of change, gradient of $f(x)$ at $P(x / f(x))$:

Definition of the first derivative:

$$m_t = f'(x) = \lim_{\Delta x \rightarrow 0} \frac{\Delta y}{\Delta x} = \frac{dy}{dx} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} = \tan(\varphi)$$



Slope on p. 16,
limits on p. 25.

10.1 Rules of Differentiation

Let $f(x)$, $u(x)$ and $v(x)$ be differentiable functions and $c \in \mathbb{R}$ a constant.

Stationary points and points of inflection, relationship between $f(x)$, $f'(x)$ and $f''(x)$:

- ▶ **Constant summand:** $f(x) = u(x) \pm c$

$$f'(x) = u'(x) \pm 0$$

- ▶ **Constant factor:** $f(x) = c \cdot u(x)$

$$f'(x) = c \cdot u'(x)$$

- ▶ **Sum rule:** $f(x) = u(x) \pm v(x)$

$$f'(x) = u'(x) \pm v'(x)$$

- ▶ **Product rule:** $f(x) = u(x) \cdot v(x)$

$$f'(x) = u'(x) \cdot v(x) + u(x) \cdot v'(x)$$

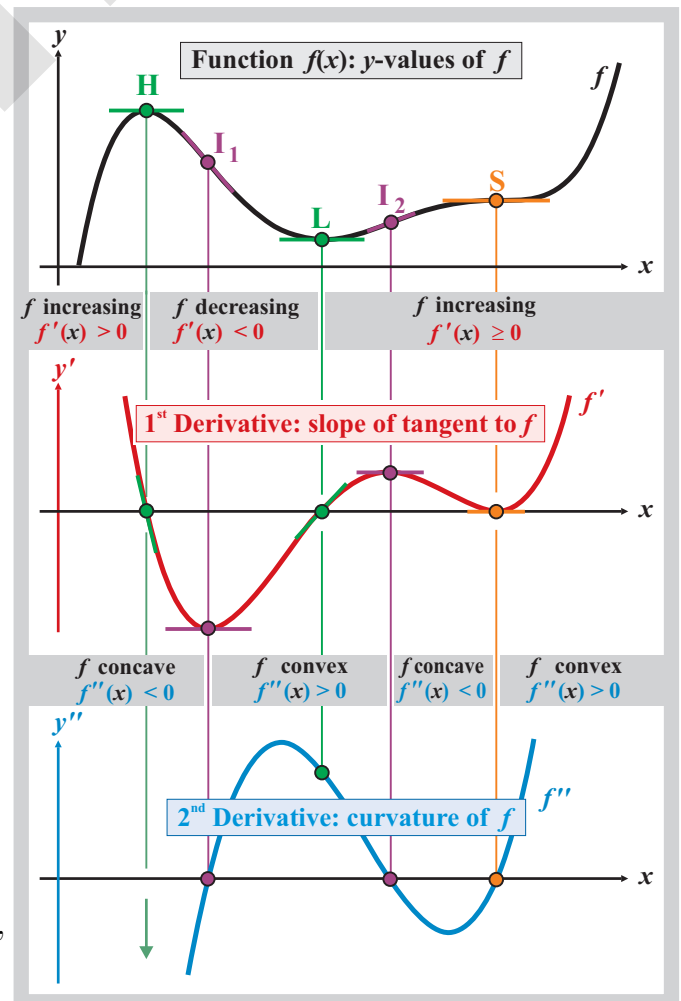
- ▶ **Quotient rule:** $f(x) = \frac{u(x)}{v(x)}$

$$f'(x) = \frac{u'(x) \cdot v(x) - u(x) \cdot v'(x)}{(v(x))^2}$$

- ▶ **Chain rule:** $f(x) = u(v(x))$

$$f'(x) = u'(v) \cdot v'(x) = \frac{du}{dv} \cdot \frac{dv}{dx}$$

”outer derivative times inner derivative”

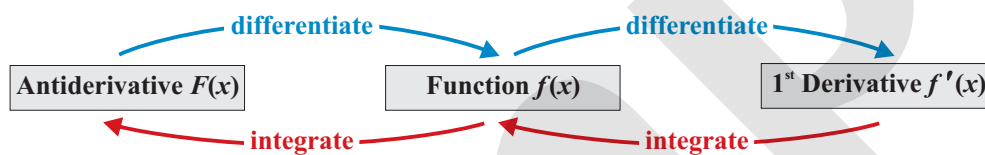


10.2 Sufficient Criteria to Calculate Particular Points

		f	f'	f''	f'''
Zero	$N(x_N / 0)$	$f(x_N) = 0$	-	-	-
High point	$H(x_H / f(x_H))$		$f'(x_H) \stackrel{\star}{=} 0$	$f''(x_H) \stackrel{\blacklozenge}{<} 0$	-
Low point	$L(x_L / f(x_L))$		$f'(x_L) \stackrel{\star}{=} 0$	$f''(x_L) \stackrel{\blacklozenge}{>} 0$	-
Stationary point of inflection	$S(x_S / f(x_S))$		$f'(x_S) \stackrel{\star}{=} 0$	$f''(x_S) \stackrel{\star}{=} 0$	$f'''(x_S) \stackrel{\blacklozenge}{\neq} 0$
Inflection point	$I(x_I / f(x_I))$		-	$f''(x_I) \stackrel{\star}{=} 0$	$f'''(x_I) \stackrel{\blacklozenge}{\neq} 0$

★ = necessary condition. (★ + ◆) = sufficient condition.

10.3 Table of Derivatives and Antiderivatives (Primitives)



$\frac{x^{n+1}}{n+1} \quad [n \neq -1]$	x^n	$n \cdot x^{n-1}$
$\ln x $	$\frac{1}{x} = x^{-1}$	$-x^{-2} = -\frac{1}{x^2}$
$\frac{2}{3} \cdot x^{\frac{3}{2}}$	$\sqrt{x} = x^{\frac{1}{2}}$	$\frac{1}{2 \cdot \sqrt{x}}$
e^x	e^x	e^x
$x \cdot (\ln x - 1)$	$\ln x $	$\frac{1}{x} = x^{-1}$
$\frac{1}{\ln(a)} \cdot a^x$	a^x	$a^x \cdot \ln(a)$
$\frac{x}{\ln(a)} \cdot (\ln x - 1)$	$\log_a x $	$\frac{1}{x \cdot \ln(a)}$
Note: Variable x in radians! Trigonometric functions on p. 19, 20.		
$-\cos(x)$	$\sin(x)$	$\cos(x)$
$\sin(x)$	$\cos(x)$	$-\sin(x)$
$-\ln(\cos(x))$	$\tan(x)$	$\frac{1}{\cos^2(x)} = 1 + \tan^2(x)$
$x \cdot \arcsin(x) + \sqrt{1-x^2}$	$\arcsin(x)$	$\frac{1}{\sqrt{1-x^2}}$
$x \cdot \arccos(x) - \sqrt{1-x^2}$	$\arccos(x)$	$-\frac{1}{\sqrt{1-x^2}}$
$x \cdot \arctan(x) - \frac{\ln(x^2+1)}{2}$	$\arctan(x)$	$\frac{1}{x^2+1}$

11 Integral Calculus

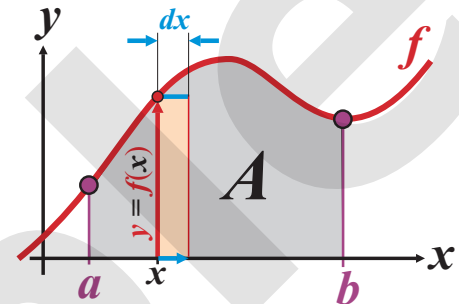
Let $F(x)$ be an **antiderivative (primitive)** of $f(x)$, that is a function satisfying $F'(x) = f(x)$. Then, any further antiderivative $F_1(x)$ of $f(x)$ may differ by an additive constant only: $F_1(x) = F(x) + C$. The constant C is called **constant of integration**.

- **Indefinite integral: Set of all antiderivatives:**

$$\int f(x) dx = \{F(x) + C \mid C \in \mathbb{R}\} \text{ with constant } C.$$

- **Definite integral, Fundamental Theorem of Calculus:**

$$A = \int_a^b f(x) dx = F(b) - F(a) = [F(x)]_a^b$$



$|A|$: Area under $f(x)$ and the x -axis between the integration limits $x = a$ and $x = b$ if $f(x) \neq 0$ for all $x \in [a, b]$.

11.1 Rules of Integration

- **Constant rule:**

$$\int_a^b (c \cdot f(x)) dx = c \cdot \int_a^b f(x) dx$$

- **Sum rule:**

$$\int_a^b (u(x) \pm v(x)) dx = \int_a^b u(x) dx \pm \int_a^b v(x) dx$$

- **Orientation of integral:**

$$\int_a^b f(x) dx = - \int_b^a f(x) dx$$

- **Interval additivity:**

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$$

- **Signed area:**

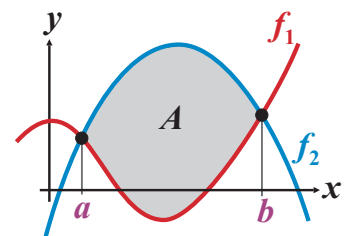
$$\left. \begin{array}{l} f(x) \geq 0 \text{ for } x \in [a, b] \\ f(x) \leq 0 \text{ for } x \in [a, b] \end{array} \right\} \Rightarrow \int_a^b f(x) dx \left\{ \begin{array}{l} \geq 0 \\ \leq 0 \end{array} \right.$$

- **Area between f_1 and f_2 :**

$$A = \int_a^b |f_2(x) - f_1(x)| dx$$

- **Integration by parts:**

$$\int_a^b u(x) \cdot v'(x) dx = [u(x) \cdot v(x)]_a^b - \int_a^b u'(x) \cdot v(x) dx$$



- **Substitution rule:** Let $f(x) = u(v(x))$ be a composite function. $U(v)$ denotes an anti-

derivative of the outer function. Then: $\int_a^b u(v(x)) \cdot v'(x) dx = \int_{v(a)}^{v(b)} u(v) dv = [U(v)]_{v(a)}^{v(b)}$

11.2 Volume of a Solid of Revolution and Arc Length

- **Rotation about x -axis:** $V_x = \pi \int_a^b (f(x))^2 dx$

generalization on p. 13.

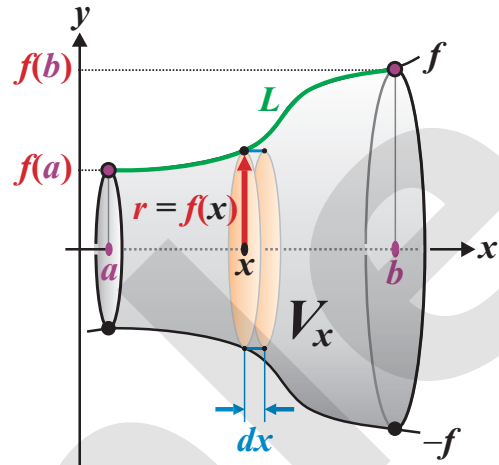
- **Rotation about y -axis:** $V_y = \pi \int_{f(a)}^{f(b)} (\bar{f}(y))^2 dy$

$y = f(x)$ strictly monotone.

$x = \bar{f}(y)$ is the inverse function of $y = f(x)$.

⇒ Inverse functions on p. 14.

- **Arc length:** $L = \int_a^b \sqrt{1 + (f'(x))^2} dx$



11.3 Power Series, Taylor Polynomials

Taylor polynomial $T_n(x)$: Approximation of a function $f(x)$ at x_0 by a polynomial of n^{th} degree:

$$T_n(x) = \sum_{k=0}^n \frac{1}{k!} f^{(k)}(x_0) (x - x_0)^k \quad \text{where } f^{(k)}(x) \text{ denotes the } k^{\text{th}} \text{ derivative of } f(x). \text{ In detail:}$$

$$T_n(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2!} f''(x_0)(x - x_0)^2 + \dots + \frac{1}{n!} f^{(n)}(x_0)(x - x_0)^n$$

Remainder term: $R_n(x) = f(x) - T_n(x) = \frac{(x-x_0)^{n+1}}{(n+1)!} f^{(n+1)}(x_0 + \alpha(x-x_0)), \quad 0 < \alpha < 1.$

Power Series:

Term	Power series	Valid for
$(1+x)^n$	$1 + \binom{n}{1}x + \binom{n}{2}x^2 + \binom{n}{3}x^3 + \dots$	$n \in \mathbb{N}; x < 1$
$\frac{1}{1+x}$	$1 - x + x^2 - x^3 \pm \dots$	$ x < 1$
$\sqrt{1+x}$	$1 + \frac{1}{2}x - \frac{1}{2 \cdot 4}x^2 + \frac{1 \cdot 3}{2 \cdot 4 \cdot 6}x^3 - \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6 \cdot 8}x^4 \pm \dots$	$ x < 1$
e^x	$1 + x + \frac{1}{2!}x^2 + \frac{1}{3!}x^3 + \frac{1}{4!}x^4 + \dots$	$x \in \mathbb{R}$
$\ln(x)$	$(x-1) - \frac{1}{2}(x-1)^2 + \frac{1}{3}(x-1)^3 \mp \dots$	$0 < x \leq 2$
$\sin(x)$	$x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 - \frac{1}{7!}x^7 \pm \dots$	$x \in \mathbb{R}$
$\cos(x)$	$1 - \frac{1}{2!}x^2 + \frac{1}{4!}x^4 - \frac{1}{6!}x^6 \pm \dots$	$x \in \mathbb{R}$
$\tan(x)$	$x + \frac{1}{3}x^3 + \frac{2}{15}x^5 + \frac{17}{315}x^7 + \dots$	$ x < \frac{\pi}{2}$
$\arcsin(x)$	$x + \frac{1}{2 \cdot 3}x^3 + \frac{1 \cdot 3}{2 \cdot 4 \cdot 5}x^5 + \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6 \cdot 7}x^7 + \dots$	$ x \leq 1$
$\arctan(x)$	$x - \frac{1}{3}x^3 + \frac{1}{5}x^5 - \frac{1}{7}x^7 \pm \dots$	$ x < 1$

12 Vector Geometry

Definition: A **vector** \vec{r}_A describes a **translation or displacement** (from O to A).

Vectors have a length (= magnitude, absolute value) and an orientation (direction). Vectors can be parallelly shifted: Vectors do not have a fixed initial point.

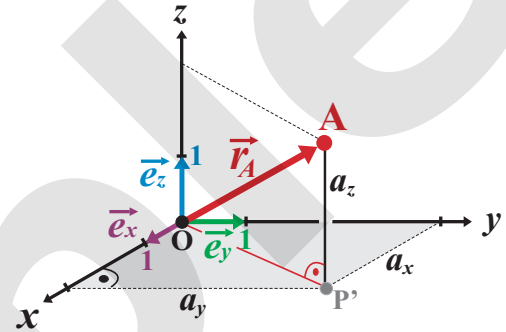
► **Standard unit vectors:**

$$\vec{e}_x = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad \vec{e}_y = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{e}_z = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

► **Linear combination:** every 3-dimensional vector \vec{r}_A can be written as a linear combination of $\vec{e}_x, \vec{e}_y, \vec{e}_z$:

$$\vec{r}_A = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} = a_x \cdot \vec{e}_x + a_y \cdot \vec{e}_y + a_z \cdot \vec{e}_z.$$

a_x, a_y, a_z are called the components of \vec{r}_A .



► **Magnitude, length:** $|\vec{r}_A| = r_A = \overline{OA} = \sqrt{a_x^2 + a_y^2 + a_z^2}$ distance from O to A.

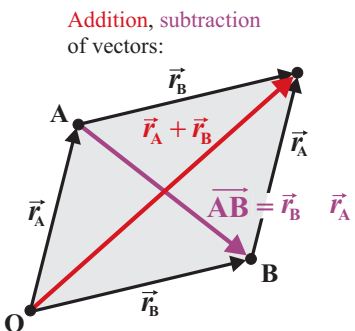
► **Position vector of A(a_x, a_y, a_z):** $\vec{r}_A = \overrightarrow{OA} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix}$: Vector from the origin to point A.

► **Addition, subtraction:**

$$\vec{r}_A \pm \vec{r}_B = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \pm \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_x \pm b_x \\ a_y \pm b_y \\ a_z \pm b_z \end{pmatrix}$$

Vector difference \overrightarrow{AB} : Position vector to the final point **minus** position vector to the initial point:

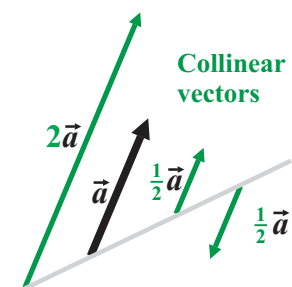
$$\overrightarrow{AB} = \vec{r}_B - \vec{r}_A$$



► **Multiplication by a scalar (number):**

Collinear vectors \vec{a} and \vec{b} :

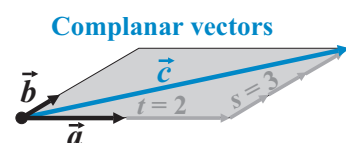
$$\vec{b} = k \cdot \vec{a} = k \cdot \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} = \begin{pmatrix} k \cdot a_x \\ k \cdot a_y \\ k \cdot a_z \end{pmatrix}$$



Complanar vectors: \vec{c} is coplanar to \vec{a} and \vec{b}

if \vec{c} can be written as a linear combination of \vec{a} and \vec{b} :

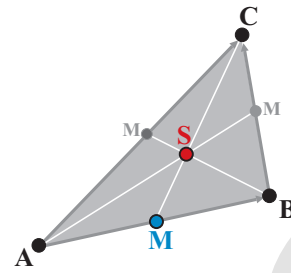
there are $t, s \in \mathbb{R}$ such that $\vec{c} = t \cdot \vec{a} + s \cdot \vec{b}$ holds.



► **Midpoint M** of A and B: $\vec{r}_M = \frac{1}{2}(\vec{r}_A + \vec{r}_B)$

► **Centroid S** of $\triangle ABC$: $\vec{r}_S = \frac{1}{3}(\vec{r}_A + \vec{r}_B + \vec{r}_C)$

center of mass, centroid see p. 7.

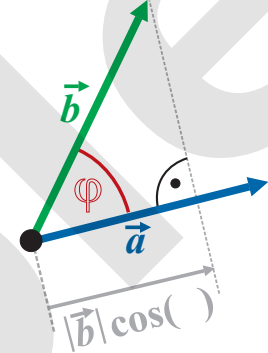


► **Scalar product (dot product):**

$$\vec{a} \cdot \vec{b} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \cdot \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = a_x b_x + a_y b_y + a_z b_z = |\vec{a}| \cdot |\vec{b}| \cdot \cos(\varphi)$$

► **Angle φ** between \vec{a} and \vec{b} : $\cos(\varphi) = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| \cdot |\vec{b}|}$

► **Perpendicular vectors:** $\vec{a} \perp \vec{b} \iff \vec{a} \cdot \vec{b} = 0$ if $\vec{a} \neq \vec{0}, \vec{b} \neq \vec{0}$.



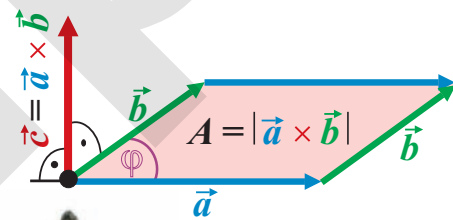
► **Vector product (cross product):**

$$\vec{c} = \vec{a} \times \vec{b} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_y b_z - a_z b_y \\ a_z b_x - a_x b_z \\ a_x b_y - a_y b_x \end{pmatrix}$$

$$\vec{c} \perp \vec{a} \text{ and } \vec{c} \perp \vec{b}$$

$$|\vec{c}| = |\vec{a} \times \vec{b}| = |\vec{a}| \cdot |\vec{b}| \cdot \sin(\varphi)$$

$|\vec{c}|$: Area of the parallelogram defined by \vec{a} and \vec{b} .

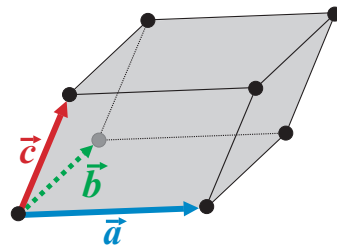


Screw \vec{c} : Rotate \vec{a} towards \vec{b} .

► **Triple product:**

$$V = |(\vec{a} \times \vec{b}) \cdot \vec{c}| = |(\vec{b} \times \vec{c}) \cdot \vec{a}| = |(\vec{c} \times \vec{a}) \cdot \vec{b}|$$

$|V|$: Volume of the parallelepiped defined by the vectors \vec{a}, \vec{b} and \vec{c} .

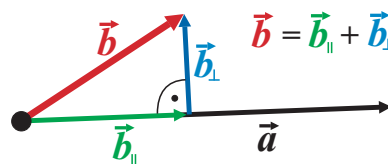


► **Unit vector in the direction of \vec{a} :** $\vec{e}_a = \frac{\vec{a}}{|\vec{a}|}$

► **Decomposition of \vec{b}** into vectorial components **parallel** and **perpendicular** to \vec{a} :

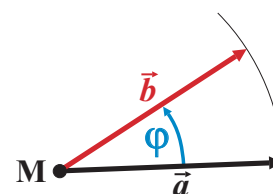
$$\vec{b}_{\parallel} = \frac{(\vec{b} \cdot \vec{a})}{|\vec{a}|^2} \cdot \vec{a}$$

$$\vec{b}_{\perp} = \vec{b} - \frac{(\vec{b} \cdot \vec{a})}{|\vec{a}|^2} \cdot \vec{a}$$



► **Rotation of a twodimensional vector $\vec{a} = \begin{pmatrix} x \\ y \end{pmatrix}$:**

$$\vec{b} = \begin{pmatrix} x \cos(\varphi) - y \sin(\varphi) \\ x \sin(\varphi) + y \cos(\varphi) \end{pmatrix}$$



12.1 Lines (see p. 16)

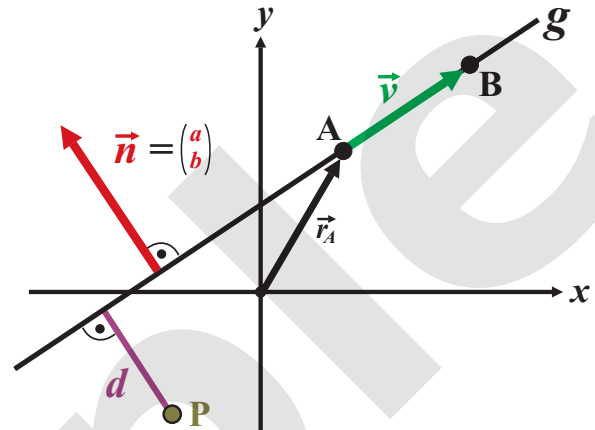
► **Cartesian form:** $g : a \cdot x + b \cdot y + c = 0$

- **Normal vector:** $\vec{n} = \begin{pmatrix} a \\ b \end{pmatrix} \perp g$
- **Parallel:** $g_1 \parallel g_2 \Leftrightarrow \vec{n}_1 = k \cdot \vec{n}_2$
- **Perpendicular:** $g_1 \perp g_2 \Leftrightarrow \vec{n}_1 \cdot \vec{n}_2 = 0$
- **Angle of intersection g_1, g_2 :**

$$\cos(\varphi) = \frac{|\vec{n}_1 \cdot \vec{n}_2|}{|\vec{n}_1| \cdot |\vec{n}_2|}$$

- **Distance of point $P(x_P / y_P)$ to g :**

$$d(P, g) = \frac{|a \cdot x_P + b \cdot y_P + c|}{\sqrt{a^2 + b^2}}$$



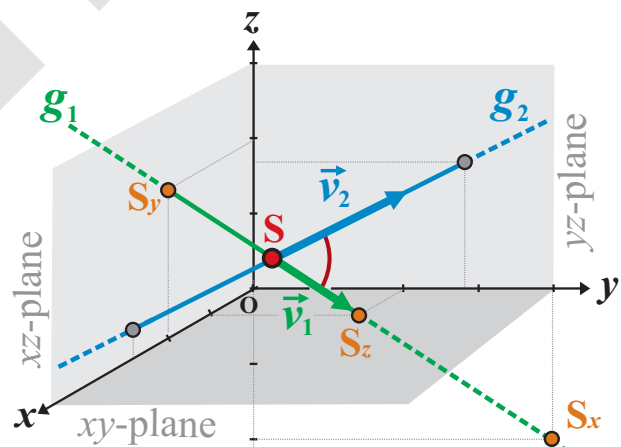
► Normal form, point-slope form see p. 16.

► **Vector equation:** $g : t \mapsto \vec{r} = \vec{r}_A + t \cdot \vec{v}$

- **Direction vector \vec{v} :** Arbitrary vector in the direction of g .
- **Support point:** Arbitrary point A on g .
- **Parallel:** $g_1 \parallel g_2 \Leftrightarrow \vec{v}_1 = k \cdot \vec{v}_2$
- **Perpendicular:** $g_1 \perp g_2 \Leftrightarrow \vec{v}_1 \cdot \vec{v}_2 = 0$
- **Angle of intersection g_1, g_2 :**

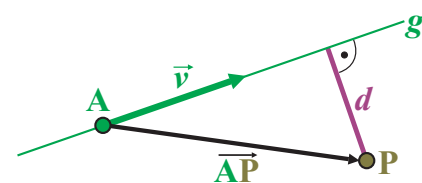
$$\cos(\varphi) = \frac{|\vec{v}_1 \cdot \vec{v}_2|}{|\vec{v}_1| \cdot |\vec{v}_2|}$$

- **Track points S_x, S_y, S_z :** Intersections of g with one of the main planes.



► **Distance between point P and line**

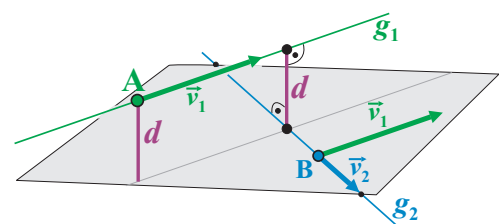
$g : \vec{r} = \vec{r}_A + t \cdot \vec{v}$ in space: $d(P, g) = \frac{|\vec{v} \times \vec{AP}|}{|\vec{v}|}$



► **Distance of two skew lines in space**

$g_1 : \vec{r} = \vec{r}_A + t \cdot \vec{v}_1$ and $g_2 : \vec{r} = \vec{r}_B + t \cdot \vec{v}_2$

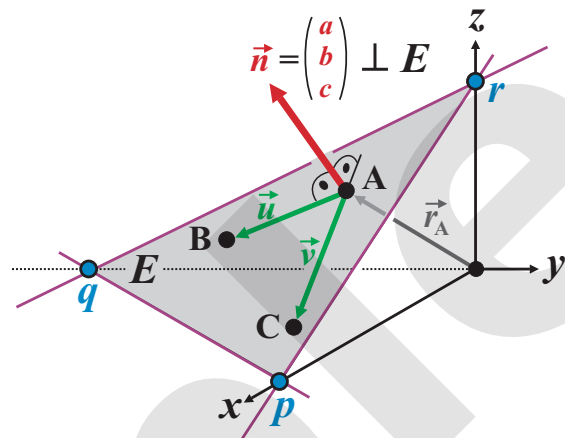
in space: $d(g_1, g_2) = \frac{|(\vec{v}_1 \times \vec{v}_2) \cdot (\vec{r}_B - \vec{r}_A)|}{|\vec{v}_1 \times \vec{v}_2|}$



12.2 Planes

► **Vector equation:** $E : \vec{r} = \vec{r}_A + t \cdot \vec{u} + s \cdot \vec{v}$

- If 3 points A, B, C or a support point A (position vector \vec{r}_A) and two independent directions $\vec{u} = \overrightarrow{AB}$ and $\vec{v} = \overrightarrow{AC}$ are known.
- Each pair $t, s \in \mathbb{R}$ corresponds to exactly one point P(x / y / z) with position vector \vec{r} on E.



► **Intercept form:** $E : \frac{x}{p} + \frac{y}{q} + \frac{z}{r} = 1$ with the intercepts $\begin{cases} p, q, r \neq 0, \\ p, q, r = \infty \text{ is allowed.} \end{cases}$

► **Normal form:** $E : \vec{n} \cdot (\vec{r} - \vec{r}_A) = 0$ with point $A \in E$ and $\vec{n} \perp E$.

► **Cartesian form:** $E : a \cdot x + b \cdot y + c \cdot z + d = 0$

- **Normal vector:**

$$\vec{n} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} = (\vec{u} \times \vec{v}) \perp E$$

- $E_1 \parallel E_2 \iff \vec{n}_1 = k \cdot \vec{n}_2$

- $E_1 \perp E_2 \iff \vec{n}_1 \cdot \vec{n}_2 = 0$

- Angle φ between E_1 and E_2 :

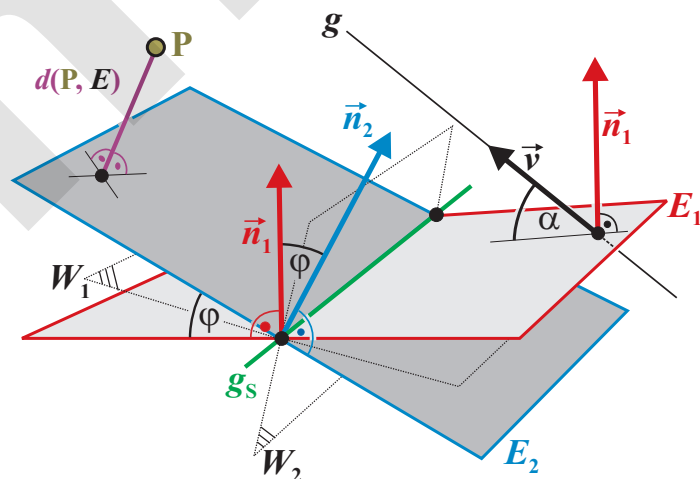
$$\cos(\varphi) = \frac{|\vec{n}_1 \cdot \vec{n}_2|}{|\vec{n}_1| \cdot |\vec{n}_2|} \quad 0 \leq \varphi \leq 90^\circ.$$

- Angle α between E_1 and g :

$$\sin(\alpha) = \frac{|\vec{n}_1 \cdot \vec{v}|}{|\vec{n}_1| \cdot |\vec{v}|} \quad 0 \leq \alpha \leq 90^\circ.$$

- Hesse's normal form:

$$H(x, y, z) = \frac{a \cdot x + b \cdot y + c \cdot z + d}{\sqrt{a^2 + b^2 + c^2}} = 0$$



- Distance P(u / v / w) to E_1 :

$$d(P, E) = \frac{|a \cdot u + b \cdot v + c \cdot w + d|}{\sqrt{a^2 + b^2 + c^2}}$$

- Angle bisector planes:

$$W_{1,2} : H_1(x, y, z) = \pm H_2(x, y, z)$$

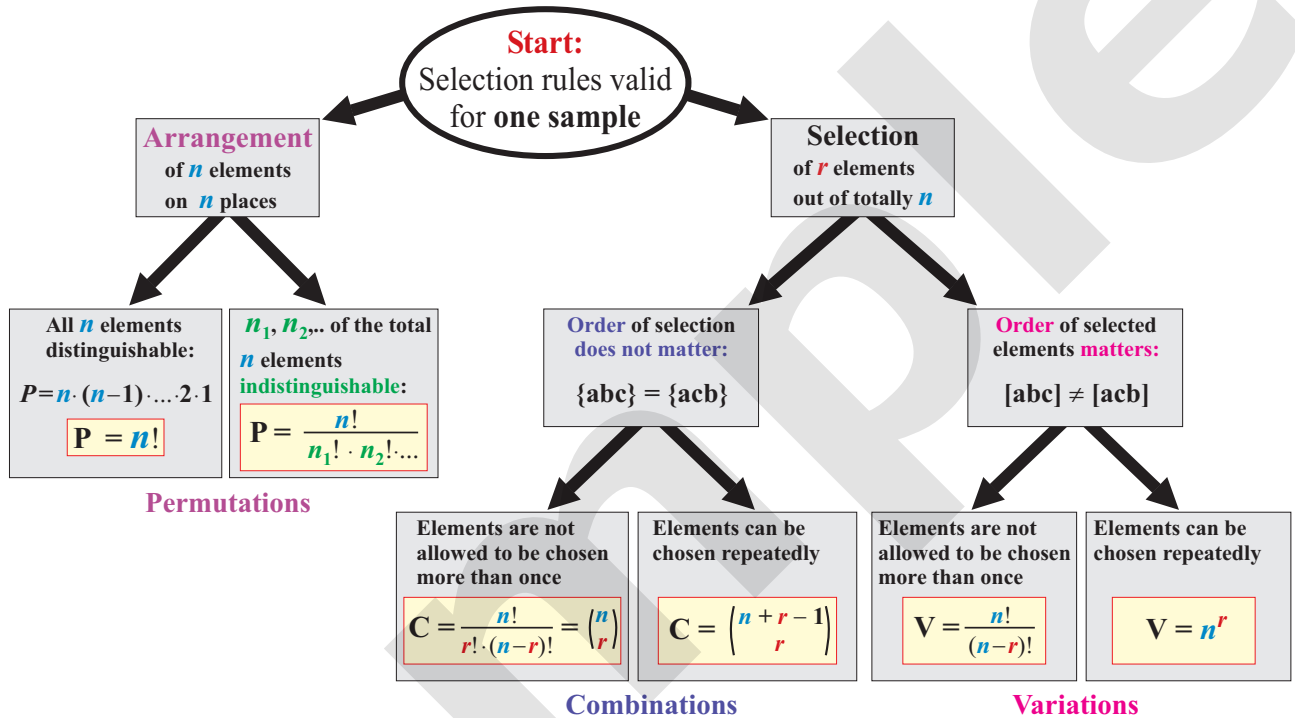
► Tangent plane to a sphere see p. 12.

13 Stochastics

13.1 Combinatorics

Factorial: $n! := 1 \cdot 2 \cdot \dots \cdot n$ $0! := 1; \quad 1! := 1$

Binomial coefficient: $\binom{n}{r} := \frac{n!}{r! \cdot (n-r)!}$



Symmetry: $\binom{n}{r} = \binom{n}{n-r}$. Recurrence relation: $\binom{n}{r} + \binom{n}{r+1} = \binom{n+1}{r+1}$.

13.2 Probability and Set Theory

► Sample space **S**: Set of all possible outcomes.

► Events **A, B, C**: Subsets of **S**.

Example: $S = \{0, 1, 2, 3, 4, 5, 6, 7\}$, $A = \{0, 2, 4, 6\}$, $B = \{1, 2, 3, 5\}$. $4 \in A$; $3 \notin A$.

$ A $	Cardinality	Number of elements in A
$A \cap B$	Intersection	A and B
$A \cup B$	Union	A or B
$\bar{A} = S \setminus A$	Complement	S without A
$C \subset A$	Subset	C contained in A
$\{\}, \emptyset$	Empty set	

► Laplace-probability: If all elements in **S** have the same probability to occur, then:

$$p(A) = \frac{|A|}{|S|} = \frac{\text{number of elements in } A}{\text{number of elements in } S} = \frac{\text{favorable}}{\text{possible}}$$

Impossible event $p(\emptyset) = 0$ Certain event $p(S) = 1$	$0 \leq p(A) \leq 1$
Complementary probability	$p(\bar{A}) = 1 - p(A)$ (Venn diagram on p. 36.)
Addition law	$p(A \cup B) = p(A) + p(B) - p(A \cap B)$
Conditional probability	<p>$p(B A)$: Probability that B occurs, under the condition that A has already occurred: „$A = \text{IF}, B = \text{THEN}$“:</p> $p(B A) = \frac{ A \cap B }{ A } = \frac{p(A \cap B)}{p(A)}$ <p>(Reduction of the sample-space from S to A.)</p>
Multiplication law	$p(A \cap B) = p(A) \cdot p(B A)$
Independent events	<p>Events A and B are independent if</p> $p(A \cap B) = p(A) \cdot p(B)$ holds.

⇒ Binomial distribution (Bernoulli) see p. 38.

13.3 Probability Distributions

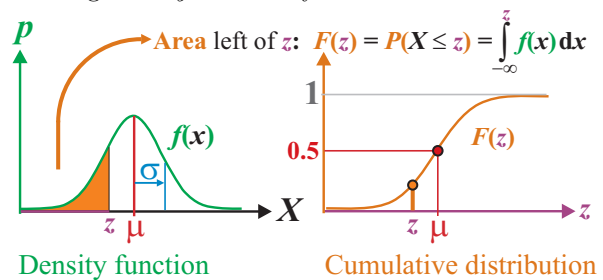
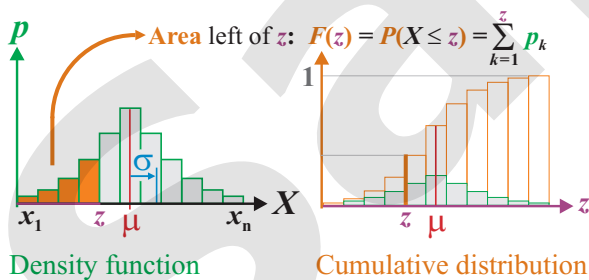
Discrete random variable:

The **random variable** X takes only and *exactly* one of the n values x_1, x_2, \dots, x_n with the **probabilities** p_1, p_2, \dots, p_n .

Continuous random variable:

The **random variable** X may take any value $x \in \mathbb{R}$. The **density function** $f(x)$ evaluates the probability for *exactly* x .

Notice: For continuous variables, the probability for observing *exactly* x is always zero.



$$p_1 + p_2 + \dots + p_n = \sum_{k=1}^n p_k = 1$$

Normalization

$$\int_{-\infty}^{\infty} f(x) dx = 1$$

$$\mu = E(X) = \sum_{k=1}^n p_k \cdot x_k$$

Expected value
(mean value)

$$\mu = E(X) = \int_{-\infty}^{\infty} f(x) \cdot x dx$$

$$\sigma^2 = \sum_{k=1}^n p_k \cdot (x_k - \mu)^2$$

Variance

$$\sigma^2 = \int_{-\infty}^{\infty} f(x) \cdot (x - \mu)^2 dx$$

$$\sigma = \sqrt{\sigma^2} = \sqrt{\text{var}(X)}$$

Standard deviation

$$\sigma = \sqrt{\sigma^2} = \sqrt{\text{var}(X)}$$

Let X, Y be two random variables and a, b constants. Then:

$$E(a \cdot X + b \cdot Y) = a \cdot E(X) + b \cdot E(Y)$$

$$\text{var}(a \cdot X + b) = a^2 \cdot \text{var}(X)$$

13.4 Binomial Distribution (discrete distribution)

The sample space of an experiment, which is repeated n times, consists of exactly two elements: $S = \{A, \bar{A}\}$ with constant probabilities $p(A) = p$ and $p(\bar{A}) = 1 - p$. Let X be the number of times A occurs in totally n repetitions. Then:

A occurs at least once	$P(X \geq 1) = 1 - (1 - p)^n$
A occurs exactly k times	$P(X = k) = \binom{n}{k} \cdot p^k \cdot (1 - p)^{n-k}$ $0 \leq k \leq n$
A occurs at most x times	$P(X \leq x) = \sum_{k=0}^x \binom{n}{k} \cdot p^k \cdot (1 - p)^{n-k}$ $0 \leq x \leq n$
Mean value, expected value	$E(X) = n \cdot p$
Standard deviation	$\sigma = \sqrt{n \cdot p \cdot (1 - p)}$

For $\sigma > 3$ the binomial distribution can be approximated by a normal distribution.

13.5 Normal Distribution (continuous distribution)

- Density function:**

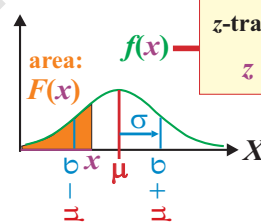
$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} = \mathcal{N}(\mu, \sigma)$$

Standardized normal distribution:

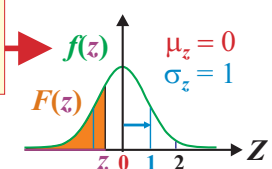
$$f(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}} = \mathcal{N}(0, 1)$$

Normal distribution

$\mathcal{N}(\mu, \sigma)$



Standardized normal distribution $\mathcal{N}(0, 1)$



z-transformation
 $z = \frac{x - \mu}{\sigma}$

Symmetry:

$$f(\mu + x) = f(\mu - x)$$

$$f(-z) = f(+z)$$

$$F(-z) = 1 - F(+z)$$

- Cumulative normal distribution:**

$$F(x) = P(X \leq x) = \frac{1}{\sqrt{2\pi}\sigma} \int_{-\infty}^x e^{-\frac{(t-\mu)^2}{2\sigma^2}} dt$$

Probability to observe *at most* x .

Standardized normal distribution:

$$F(z) = P(Z \leq z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{t^2}{2}} dt$$

\Rightarrow See table in the rear inner cover.

- σ -environments for the normal distribution:**

1 σ -environment	2 σ -environment	3 σ -environment
$p(X - \mu < 1\sigma) \approx 68.3\%$	$p(X - \mu < 2\sigma) \approx 95.4\%$	$p(X - \mu < 3\sigma) \approx 99.7\%$

13.6 Statistics: Univariate Data (one Variable)

Let $X = \{x_1, x_2, \dots, x_k\}$ the values and n_1, n_2, \dots, n_k their **absolute frequency** of a sample of size $n = \sum_{i=1}^k n_i = n_1 + n_2 + \dots + n_k$. The **relative frequencies** $p(x_i) = \frac{n_i}{n}$ behave like the Laplace-probability of observing the value x_i , particularly $\sum_{i=1}^k p(x_i) = 1$.

	Individual data	Grouped data
Data	n values x_1, x_2, \dots, x_n	k values x_1, x_2, \dots, x_k with absolute frequencies n_1, n_2, \dots, n_k
Arithmetic mean (expected value)	$\bar{x} = E(X) = \frac{1}{n} \sum_{i=1}^n x_i$	$\bar{x} = E(X) = \frac{1}{n} \sum_{i=1}^k n_i x_i = \sum_{i=1}^k p(x_i) \cdot x_i$
Median	The median $x_{0.5}$ of the values of an ordered sample is <ul style="list-style-type: none"> the value of the middle item, if n is odd. the mean of the middle two items, if n is even. 	
Mode	Value that appears most often in a set of data.	
Average linear deviation from mean	$s_m = \frac{1}{n} \sum_{i=1}^n x_i - \bar{x} $	$s_m = \frac{1}{n} \sum_{i=1}^k n_i x_i - \bar{x} $
Range	$R = x_{\max} - x_{\min}$	
Variance*	$s_x^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$	$s_x^2 = \frac{1}{n-1} \sum_{i=1}^k n_i (x_i - \bar{x})^2$ or $s_x^2 = \sum_{i=1}^k p(x_i) \cdot (x_i - \bar{x})^2 = E(X^2) - (E(X))^2$

If the values x_1, x_2, \dots, x_n represent an entire population or if we are interested in the variation within the sample itself, the denominator is n (instead of $n - 1$).

► **Standard deviation:** $s_x = \sqrt{s_x^2}$

► **Variation coefficient:** $V = \frac{s_x}{\bar{x}} \cdot 100\%$ is used to compare different samples.

► **Box plot:** Evaluate the **median** $x_{0.5}$, the upper ($x_{0.75}$) and lower ($x_{0.25}$) quartiles, the smallest (x_{\min}) and the largest (x_{\max}) sample. Graphical representation:



► **Inequality of Chebychev:**

For a sample with mean \bar{x} and variance s_x^2 , the probability p for an observation x to be found within a range of $\pm\lambda$ from the mean is given by $p(|x - \bar{x}| < \lambda) \geq 1 - \frac{s_x^2}{\lambda^2}$.

13.7 Statistics: Bivariate Data, Regression and Correlation

Let $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ be n pairs of observations. To describe the dependency between x and y , a **model function** $y = f(x)$ which depends on the parameters a, b, \dots is fitted to the data such that the mean square deviation of $y_i - f(x)$ becomes a minimum:

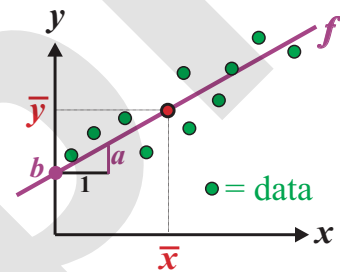
$$F(x) = \sum_{i=1}^n (y_i - f(x_i))^2 \longrightarrow \text{minimum}$$

Linear Regression:

Model function: $y = f(x) = a \cdot x + b$ with

• **Slope:**
$$a = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{c_{xy}}{s_x^2} = r_{xy} \cdot \frac{s_y}{s_x}$$

• **y-Intercept:** $b = \bar{y} - a \cdot \bar{x}$



Alternative: System of linear equations to calculate a and b of the linear regression:

$$\begin{cases} \left(\sum_{i=1}^n x_i^2 \right) \cdot a + \left(\sum_{i=1}^n x_i \right) \cdot b = \sum_{i=1}^n x_i \cdot y_i \\ \left(\sum_{i=1}^n x_i \right) \cdot a + n \cdot b = \sum_{i=1}^n y_i \end{cases}$$

Correlation coefficient:

$$r_{xy} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \cdot \sum_{i=1}^n (y_i - \bar{y})^2}} = \frac{c_{xy}}{s_x \cdot s_y}$$

Covariance:

$$c_{xy} = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

$$c_{xy} = E(X \cdot Y) - E(X) \cdot E(Y)$$

r_{xy} describes the strength of correlation between x and y :

Correlation coefficient r_{xy}			
full	strong	medium	weak to none
$ r_{xy} = 1$	$1 > r_{xy} \geq 0.7$	$0.7 > r_{xy} \geq 0.3$	$0.3 > r_{xy} \geq 0$

14 Mathematical Symbols

$A \Rightarrow B$	Implication: A implies B
$A \Leftrightarrow B$	Equivalence: A is equivalent to B
$\mathbb{N}, \mathbb{Z}, \mathbb{Q}, \mathbb{R}$	Sets of numbers (see p. 2)
\mathbb{D}, \mathbb{W}	Domain, range (see p. 14)
$f : x \mapsto y = f(x)$	y is a function of x (see p. 14)
$A = \{a, b, c, \dots\}$	Set A consisting of the elements a, b, c, \dots
$[a, b]$	Interval between (including) a and b
(a, b)	Interval between (but without) a and b example: $(2, 5] =$ set of all x , such that $2 < x \leq 5$
$5 \in \mathbb{N}$	Element: 5 is element of \mathbb{N} , that is, 5 is a natural number
$1.5 \notin \mathbb{N}$	Not element: 1.5 is not in the set \mathbb{N}
$P \in f$	Point P is on the graph of the function f
$A \subset B$	Subset: set A is part of B
$A \cap B$	A Intersect B : elements that are in A and in B
$g \cap E$	Line g intersected with plane E
$A \cup B$	A union B : elements that are in A or in B or in both.
$A \setminus B$	A without B : elements that are in A but not in B
	Condition (if). Examples: $\mathbb{D} = \{x \in \mathbb{R} \mid x \leq 1\} =$ set of all x smaller or equal 1 $p(B \mid A) =$ Probability of B to occur, if A already occurred
\forall	For all: $\forall x \in \mathbb{R} \dots$
\exists	There is: $\exists x \in \mathbb{R}$ there is a real number x such that...

The Greek Alphabet

A	α	Alpha	H	η	Eta	N	ν	Nu	T	τ	Tau
B	β	Beta	Θ	θ, ϑ	Theta	Ξ	ξ	Xi	Y	υ	Upsilon
Γ	γ	Gamma	I	ι	Iota	O	o	Omicron	Φ	ϕ, φ	Phi
Δ	δ	Delta	K	κ	Kappa	Π	π	Pi	X	χ	Chi
E	ϵ, ε	Epsilon	Λ	λ	Lambda	P	ρ	Rho	Ψ	ψ	Psi
Z	ζ	Zeta	M	μ	Mu	Σ	σ, ς	Sigma	Ω	ω	Omega

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